



(12) **United States Patent**
Elick et al.

(10) **Patent No.:** **US 9,136,055 B2**
(45) **Date of Patent:** **Sep. 15, 2015**

(54) **TAP CHANGER HAVING A VACUUM INTERRUPTER ASSEMBLY WITH AN IMPROVED DAMPER**

(71) Applicants: **Robert Alan Elick**, Jackson, TN (US);
Jon Christopher Brasher, Humboldt, TN (US)

(72) Inventors: **Robert Alan Elick**, Jackson, TN (US);
Jon Christopher Brasher, Humboldt, TN (US)

(73) Assignee: **ABB Technology AG**, Zurich (CH)

(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 29 days.

(21) Appl. No.: **14/036,834**

(22) Filed: **Sep. 25, 2013**

(65) **Prior Publication Data**

US 2014/0176273 A1 Jun. 26, 2014

Related U.S. Application Data

(63) Continuation-in-part of application No. PCT/US2012/030244, filed on Mar. 23, 2012.

(60) Provisional application No. 61/467,837, filed on Mar. 25, 2011.

(51) **Int. Cl.**
H01H 33/666 (2006.01)
H01H 9/00 (2006.01)
H01F 29/04 (2006.01)
H01H 3/60 (2006.01)
H01H 3/30 (2006.01)

(52) **U.S. Cl.**
CPC **H01F 29/04** (2013.01); **H01H 3/605** (2013.01); **H01H 9/0027** (2013.01); **H01H 9/0038** (2013.01); **H01H 33/6661** (2013.01); **H01H 3/3015** (2013.01)

(58) **Field of Classification Search**

CPC H01H 1/18; H01H 19/12; H01H 9/0016; H01H 33/66661; H01F 29/04
USPC 218/153, 134; 200/11 J, 11 TC, 400; 323/258, 343; 336/94
See application file for complete search history.

(56) **References Cited**

U.S. PATENT DOCUMENTS

3,553,395	A	1/1971	White	
5,107,200	A	4/1992	Dohnal et al.	
5,191,179	A	3/1993	Yatchum et al.	
5,877,465	A *	3/1999	Perret	218/60
6,060,669	A	5/2000	Dohnal et al.	
6,347,615	B1 *	2/2002	Hopfl et al.	123/447

(Continued)

FOREIGN PATENT DOCUMENTS

WO	2012134958	A1	10/2012
WO	2012134963	A1	10/2012
WO	2012134977	A1	10/2012

Primary Examiner — Renee Luebke

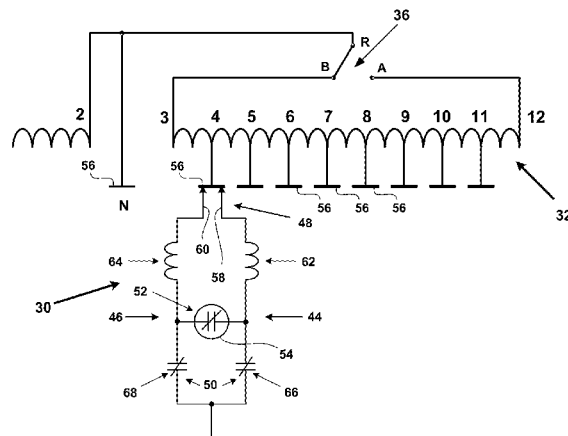
Assistant Examiner — William Bolton

(74) *Attorney, Agent, or Firm* — Paul R. Katterle

(57) **ABSTRACT**

An on-load tap changer is provided having a vacuum interrupter that is actuated by a shaft of an actuation assembly. A damper dampens the movement of the shaft. The damper provides more dampening when the shaft is closing the vacuum interrupter than when the shaft is opening the vacuum interrupter. The damper includes a housing at least partially defining an interior chamber into which the shaft extends. A piston with openings extending therethrough is disposed in the interior chamber and is secured to the shaft so as to be movable therewith. A blocking structure is operable to block the openings in the piston when the shaft is closing the vacuum interrupter and to un-block the openings in the piston when the shaft is opening the vacuum interrupter.

20 Claims, 18 Drawing Sheets



(56)	References Cited		2003/0168433 A1 *	9/2003	Kurzmann	218/157
	U.S. PATENT DOCUMENTS		2005/0016962 A1 *	1/2005	Loebner et al.	218/84
	7,842,122 B2	11/2010	Golner et al.	* cited by examiner		

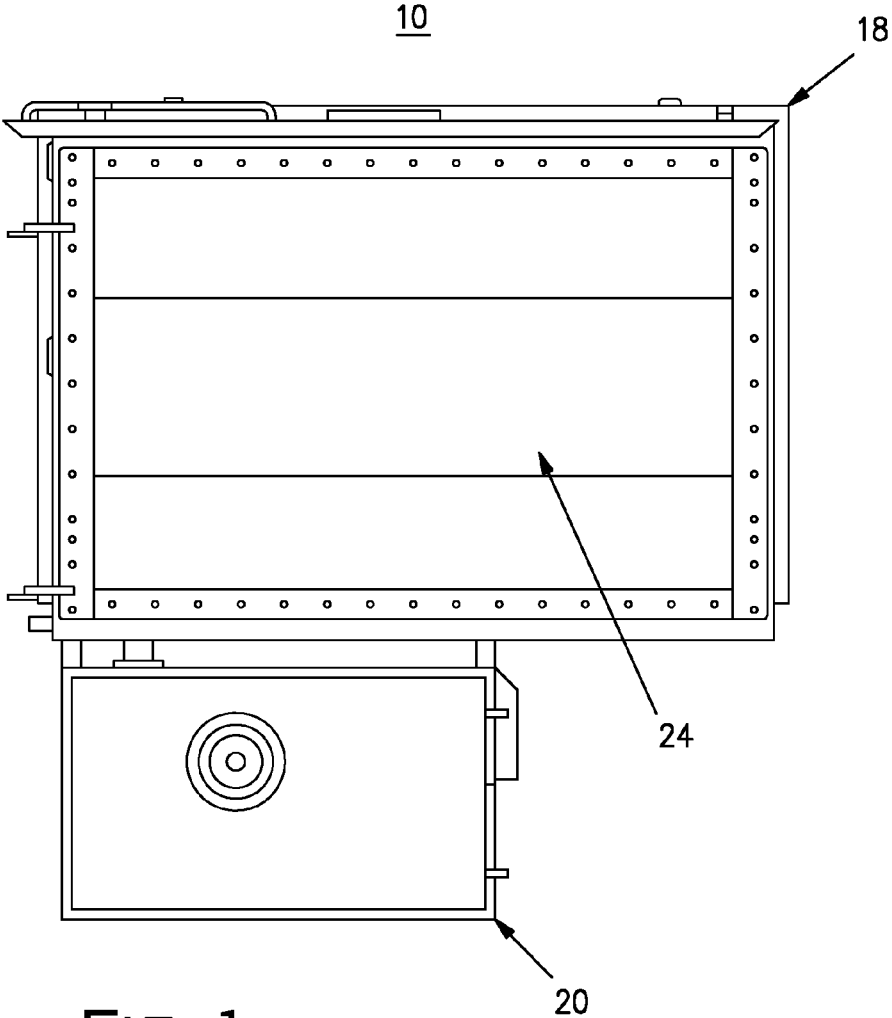
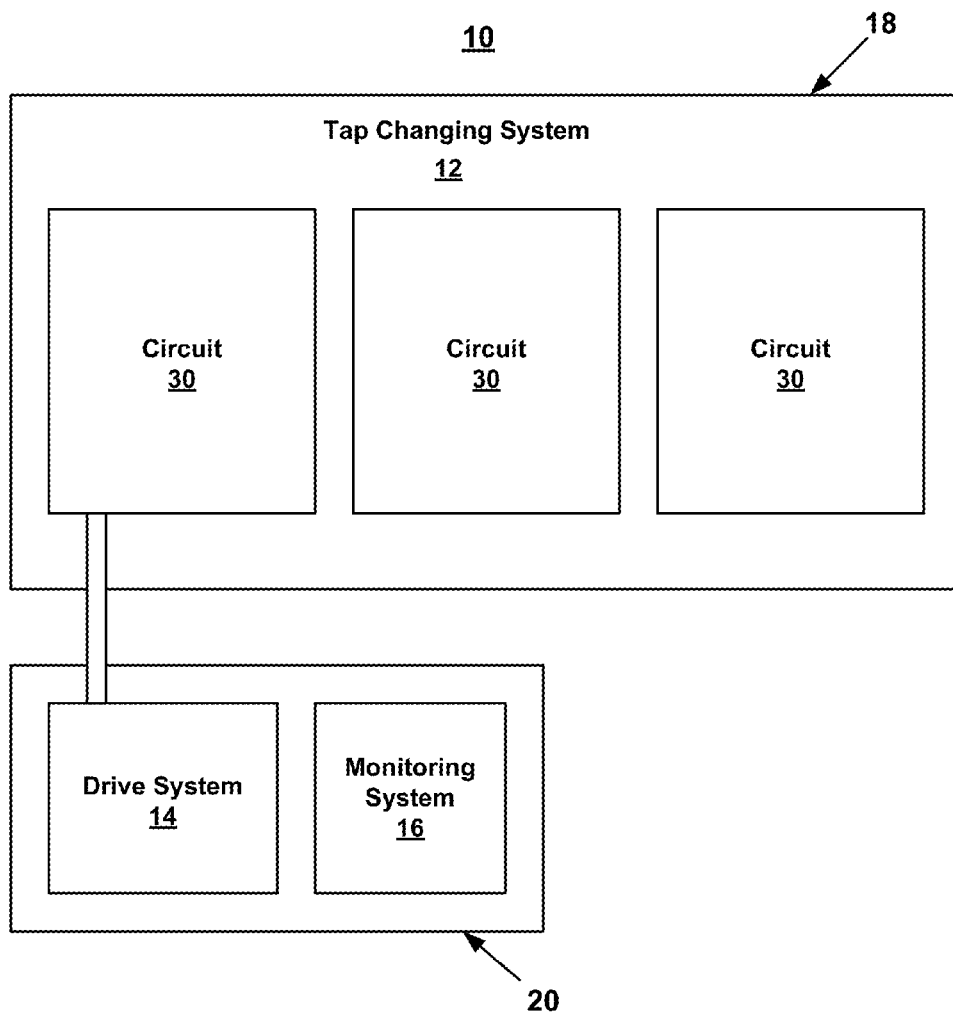


FIG. 1

**Fig. 2**

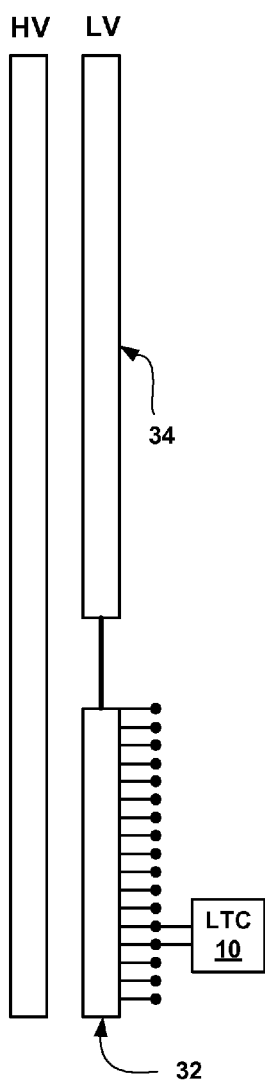


Fig. 3A

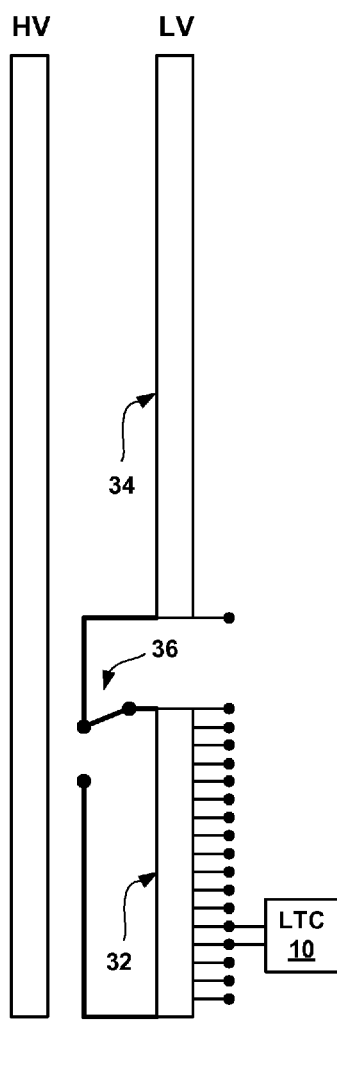


Fig. 3B

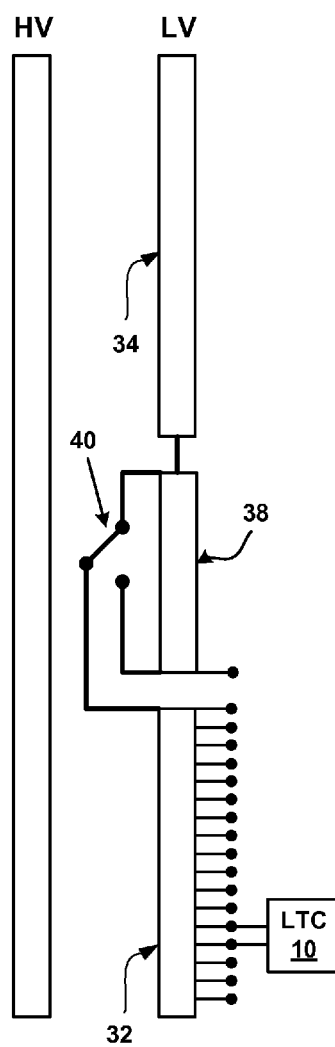


Fig. 3C

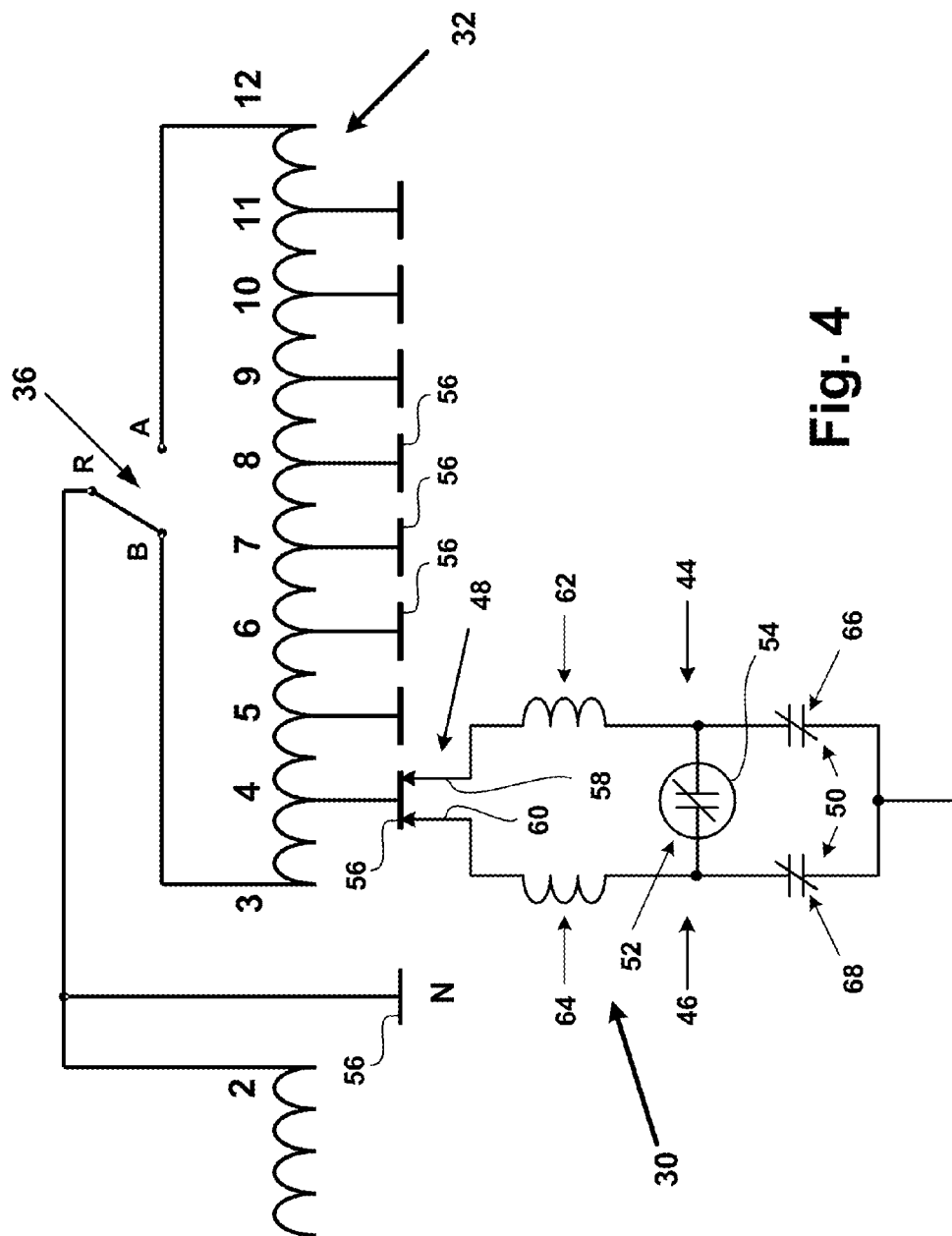
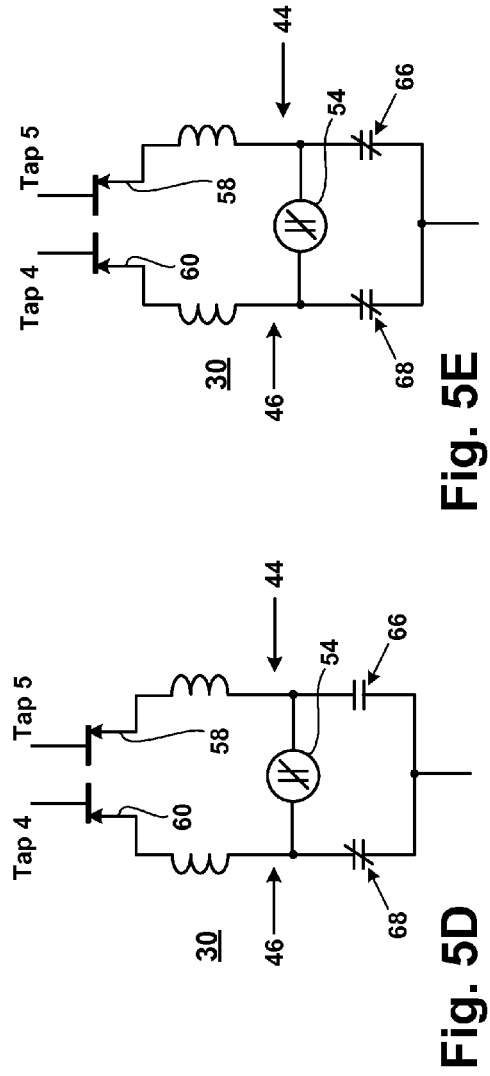
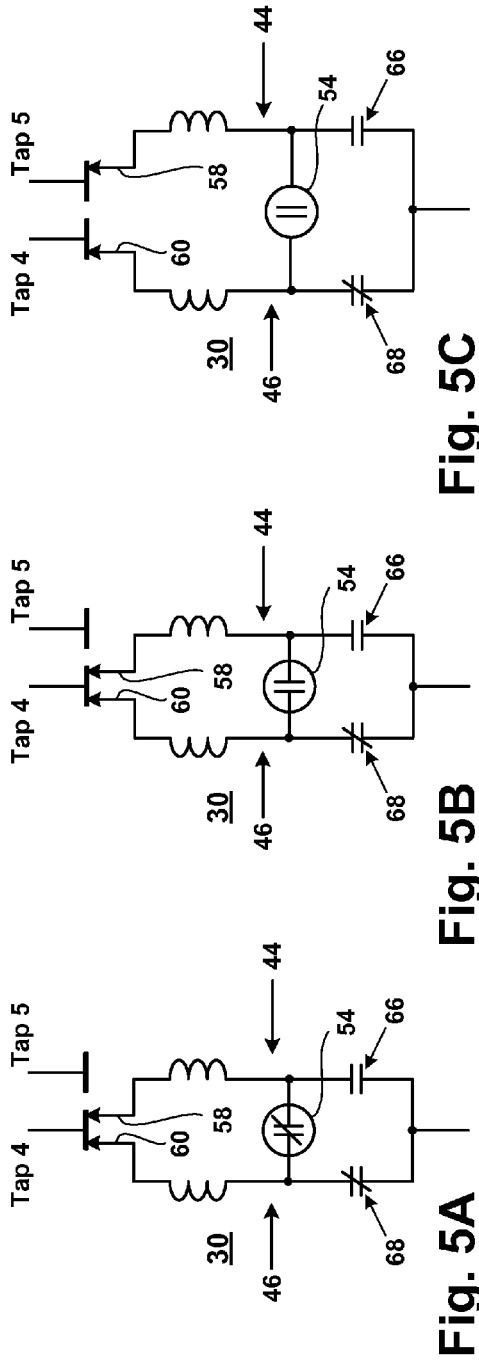
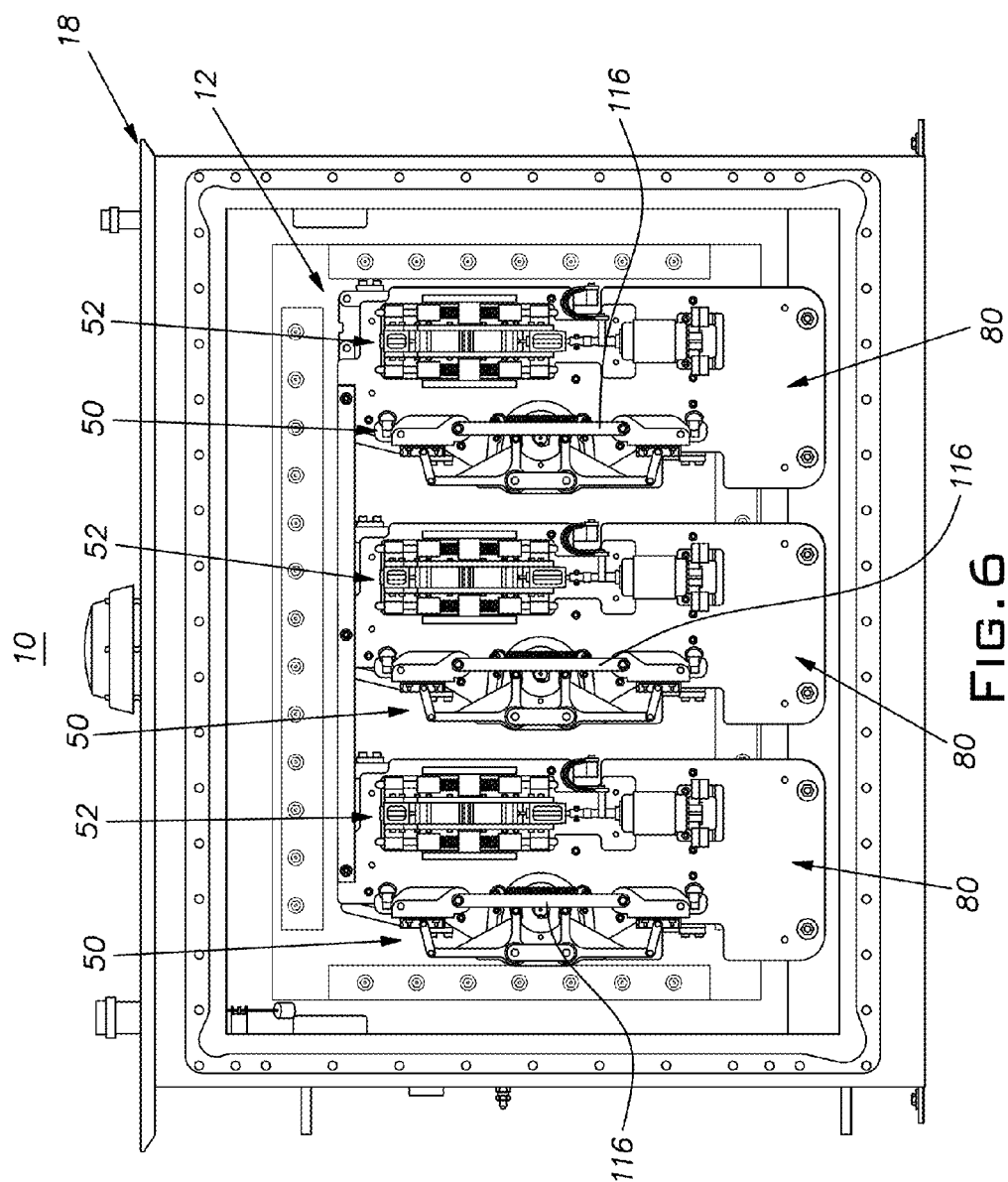


Fig. 4





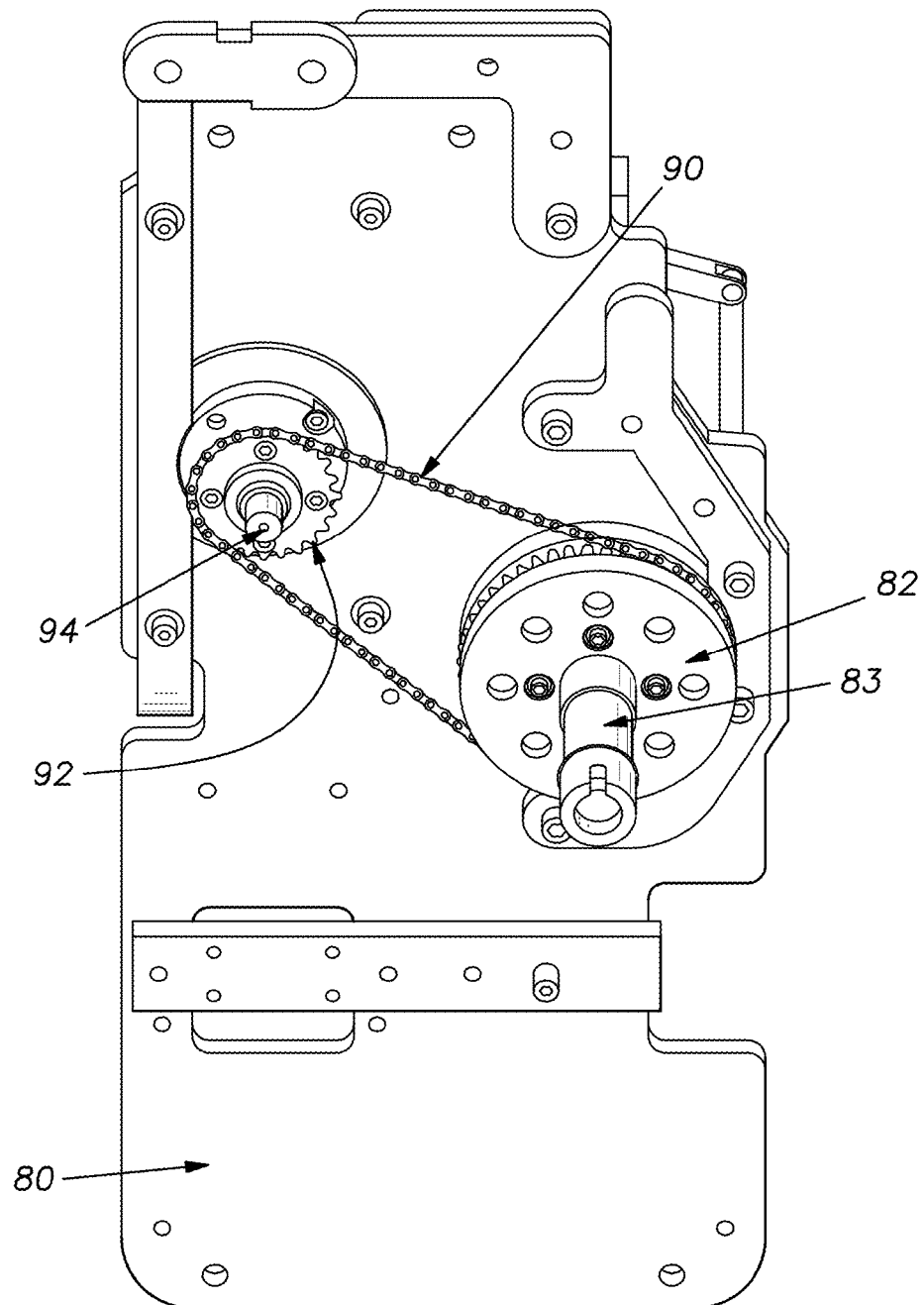


FIG. 7

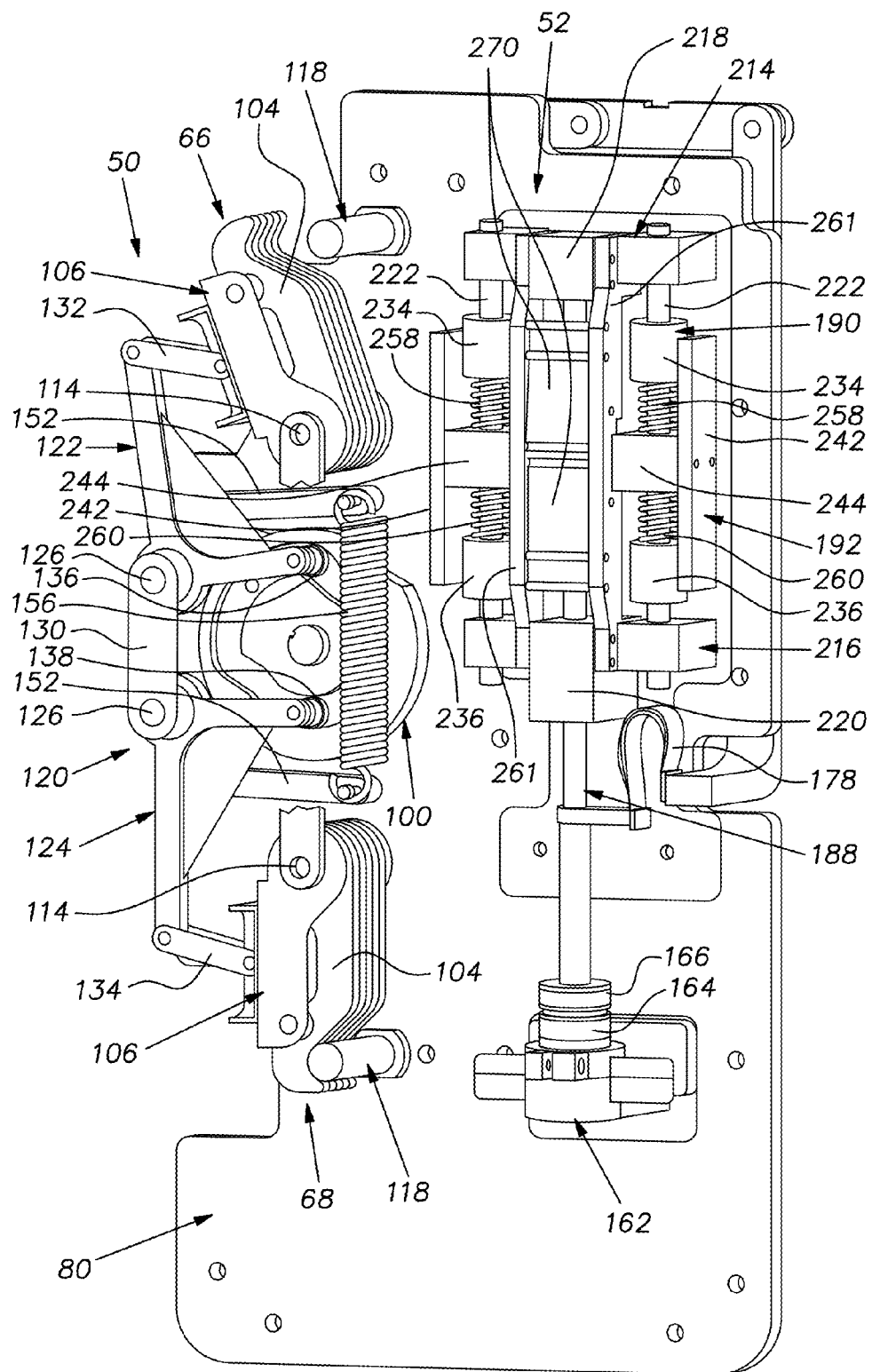


FIG. 8

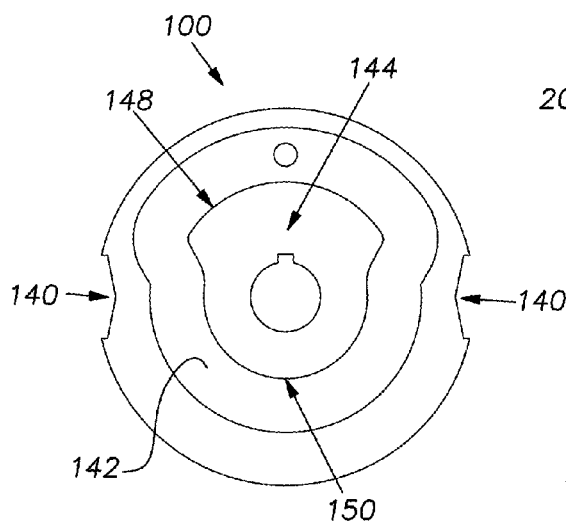


FIG. 9

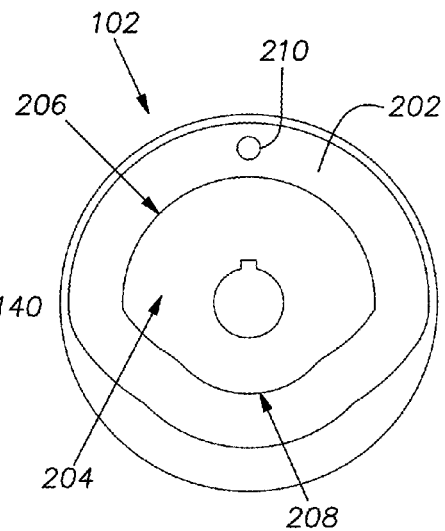


FIG. 11

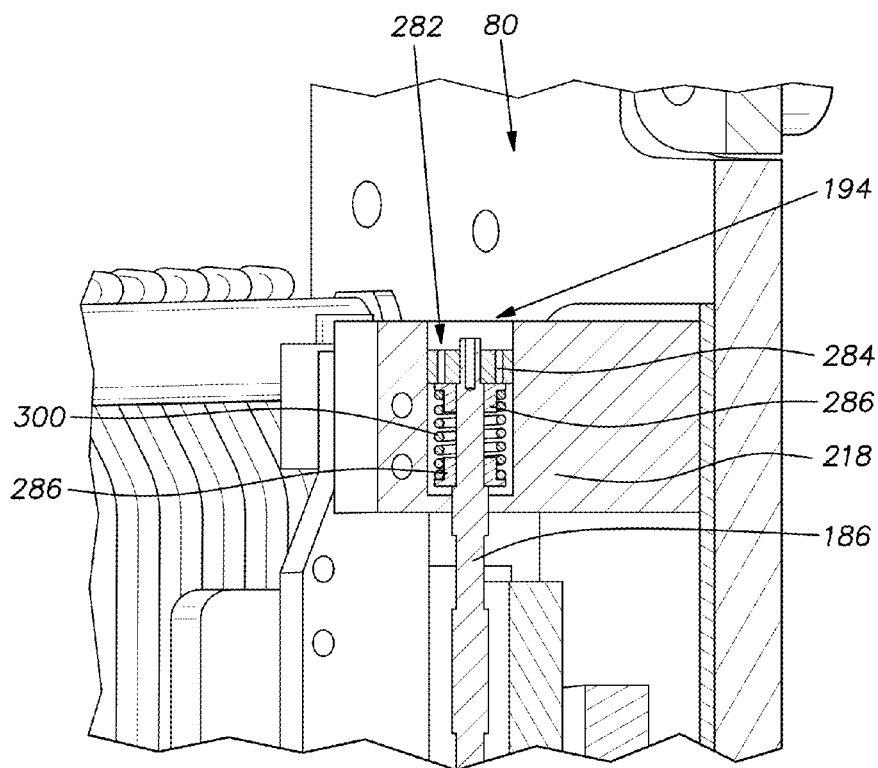


FIG. 15

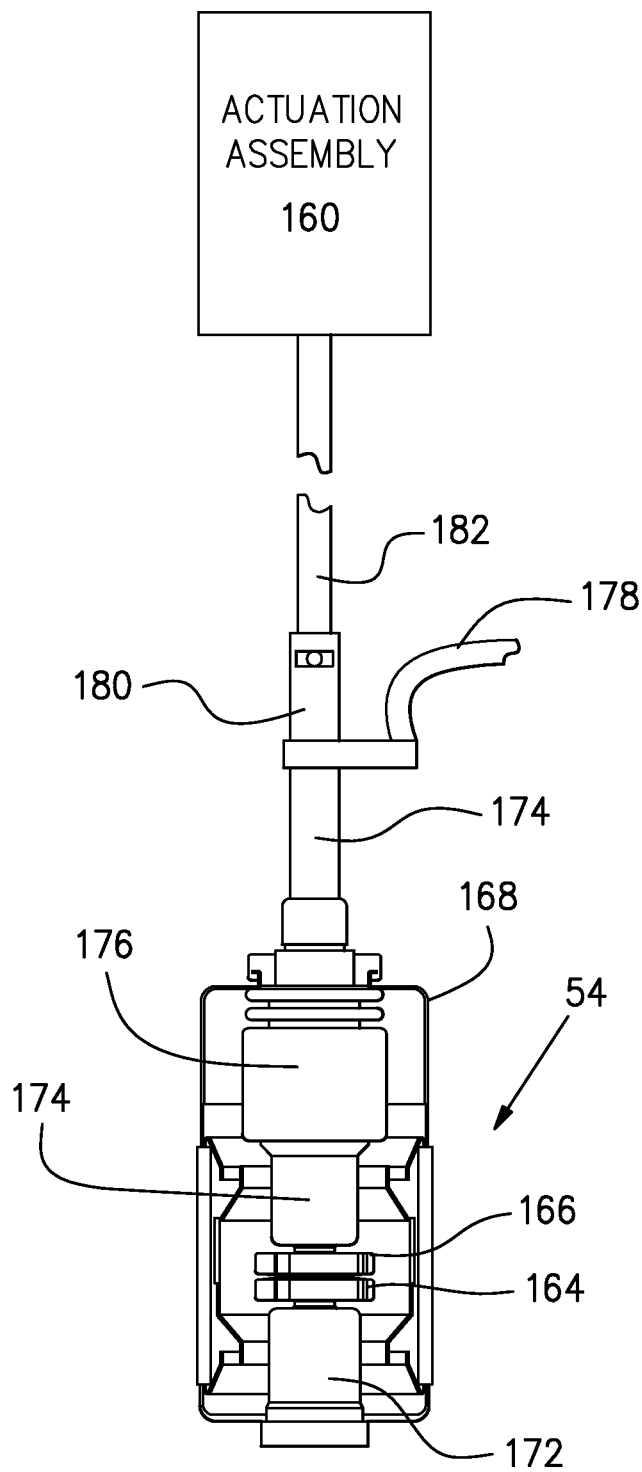


FIG. 10

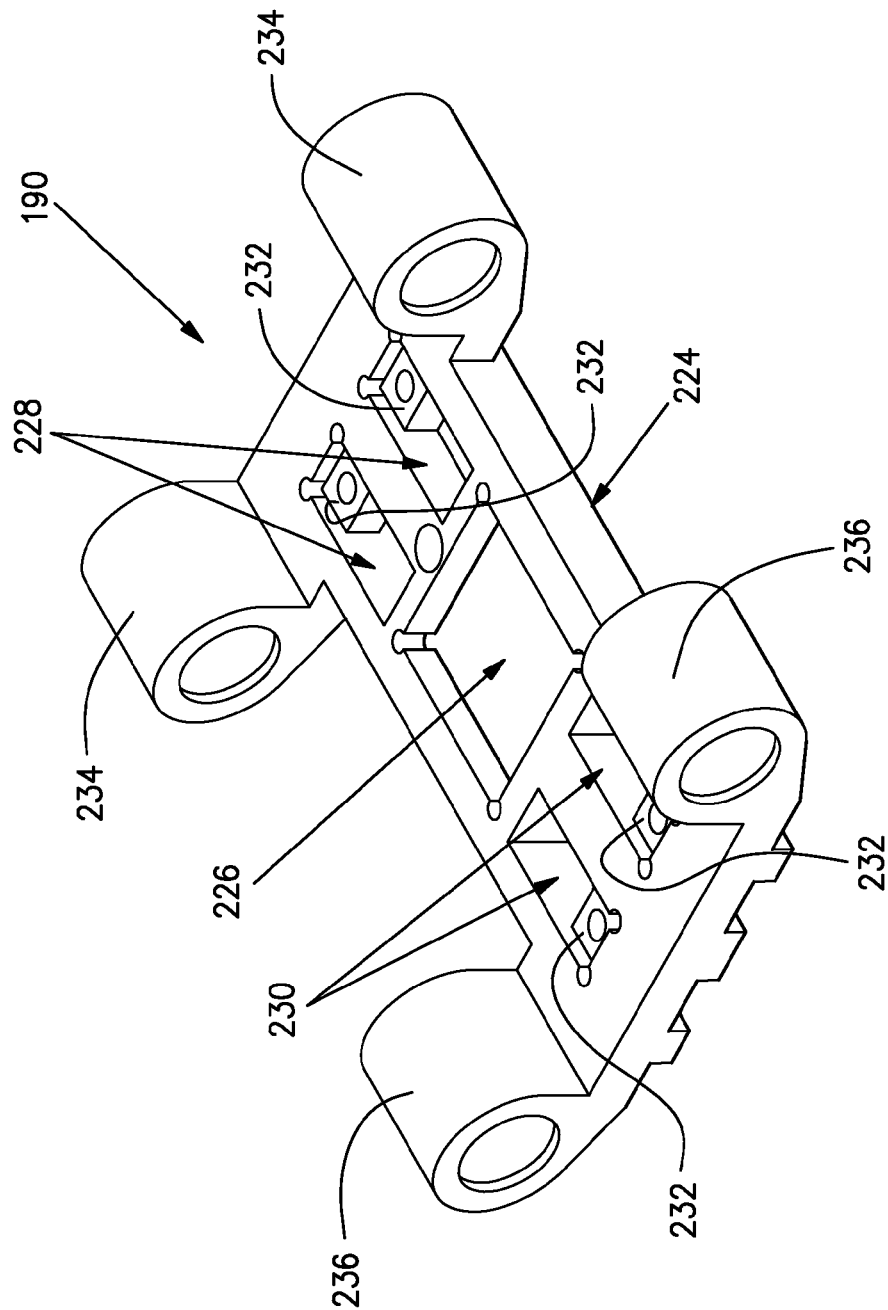


FIG. 12

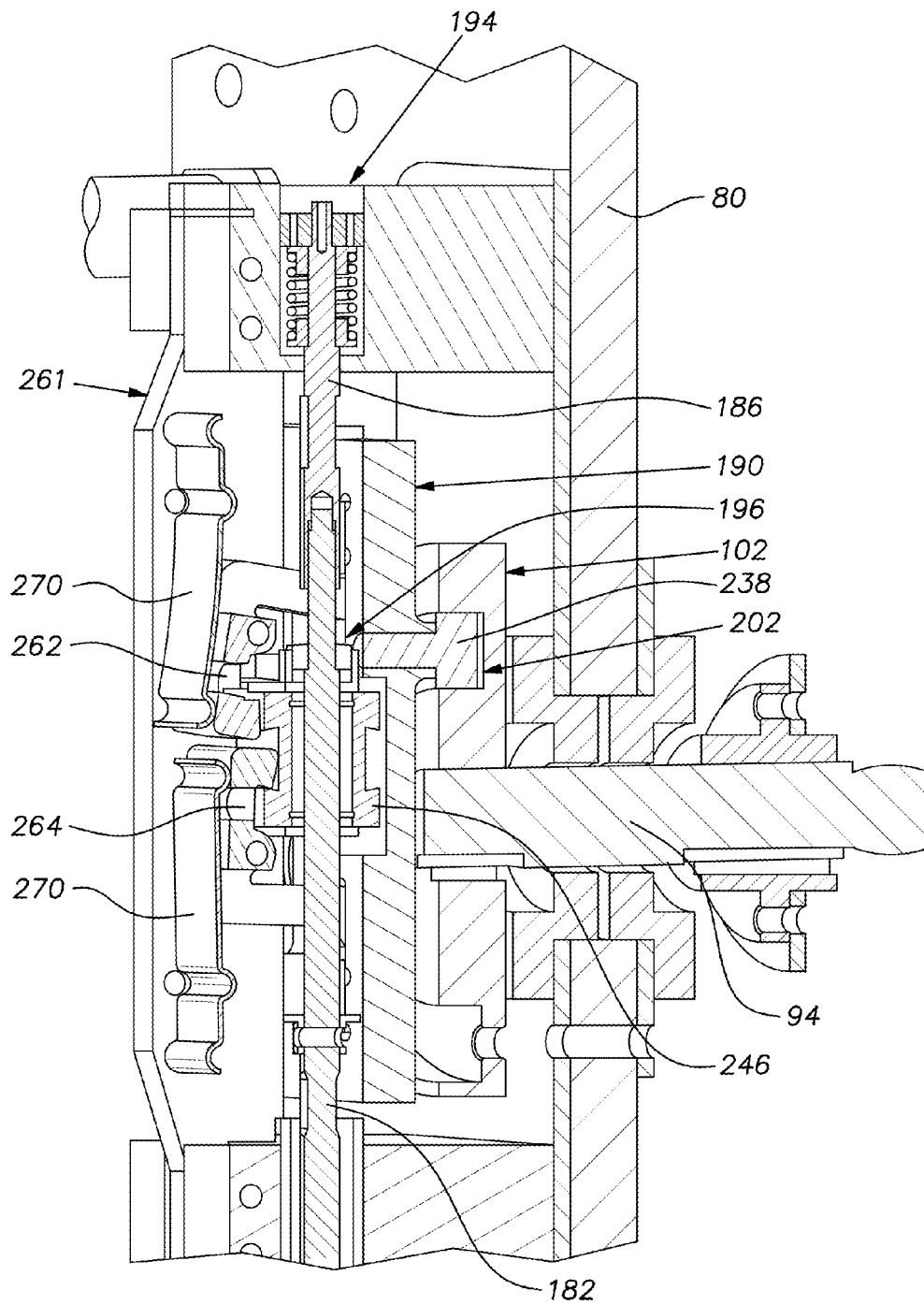


FIG. 13

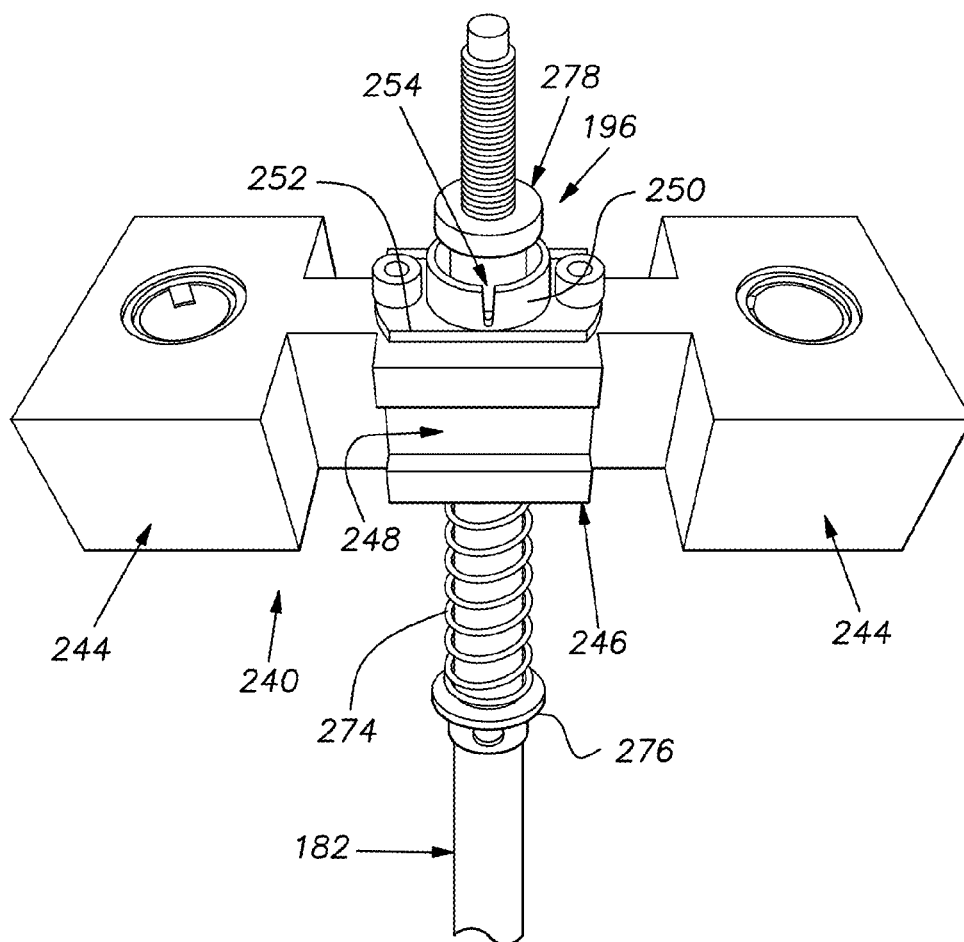


FIG. 14

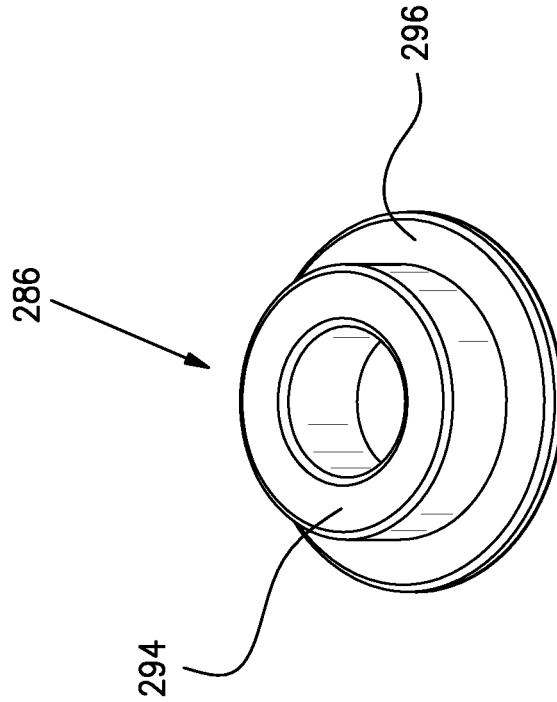


FIG. 17

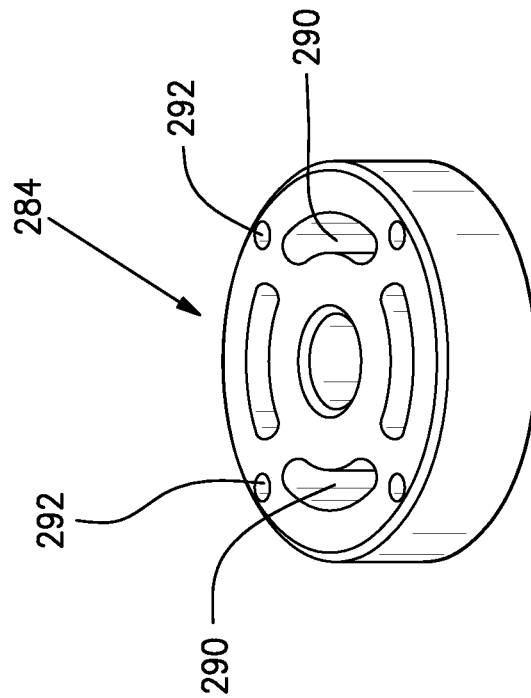
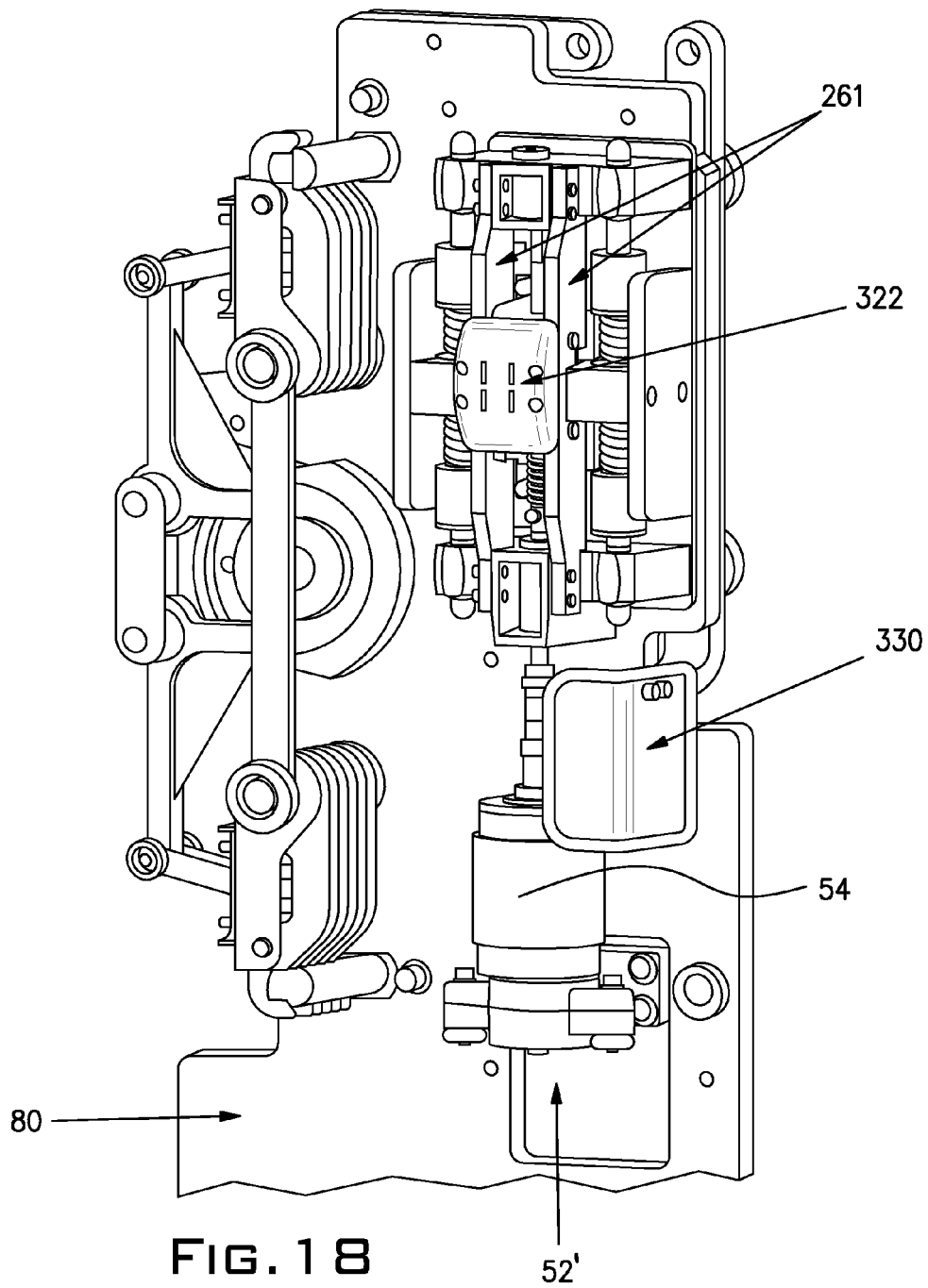
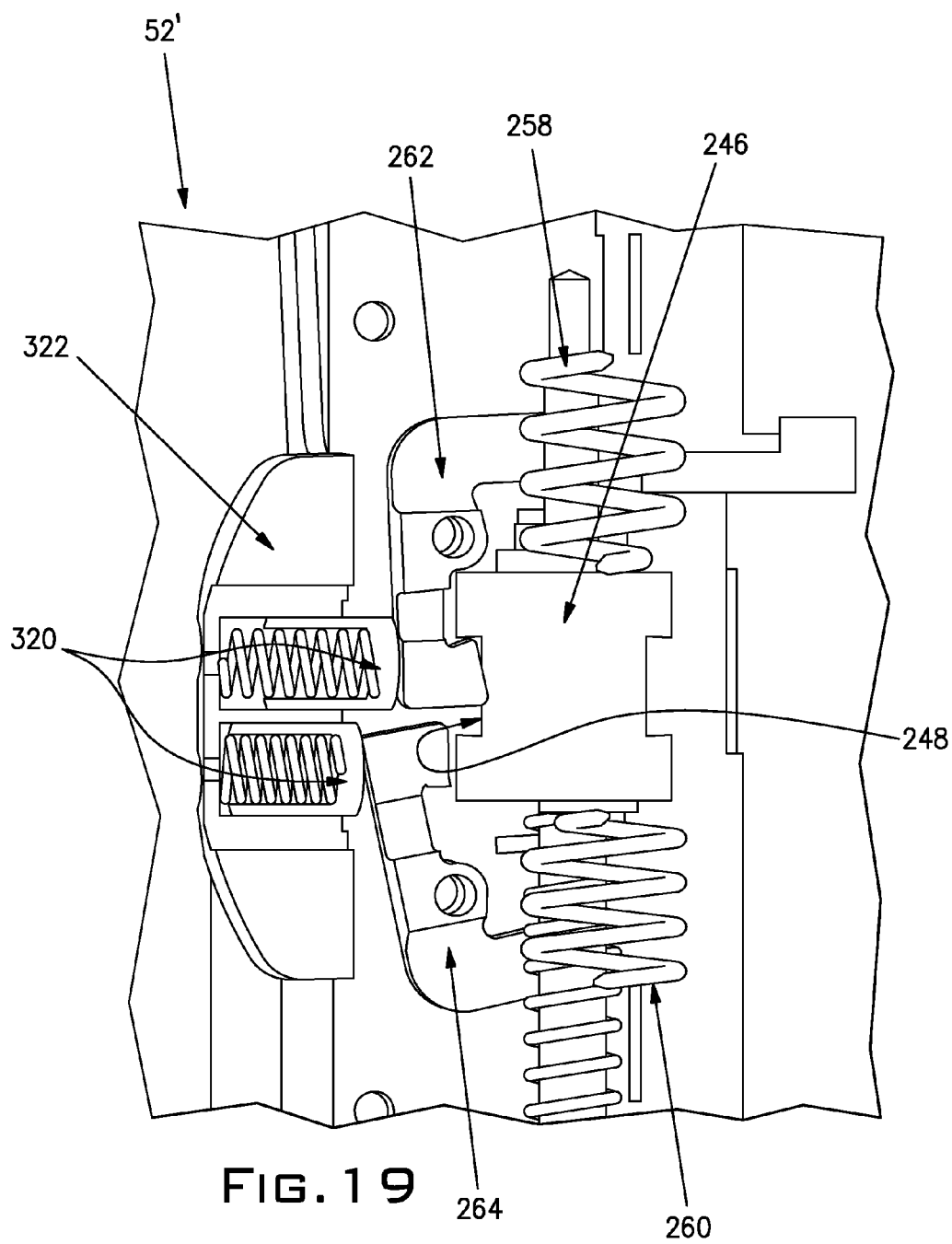


FIG. 16





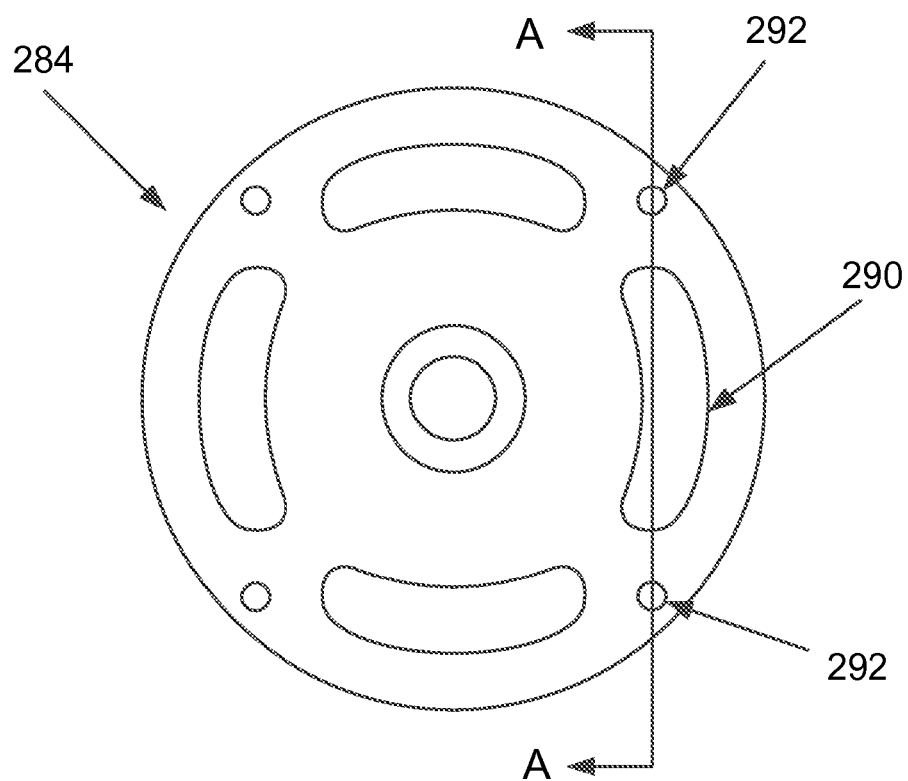


FIG. 20

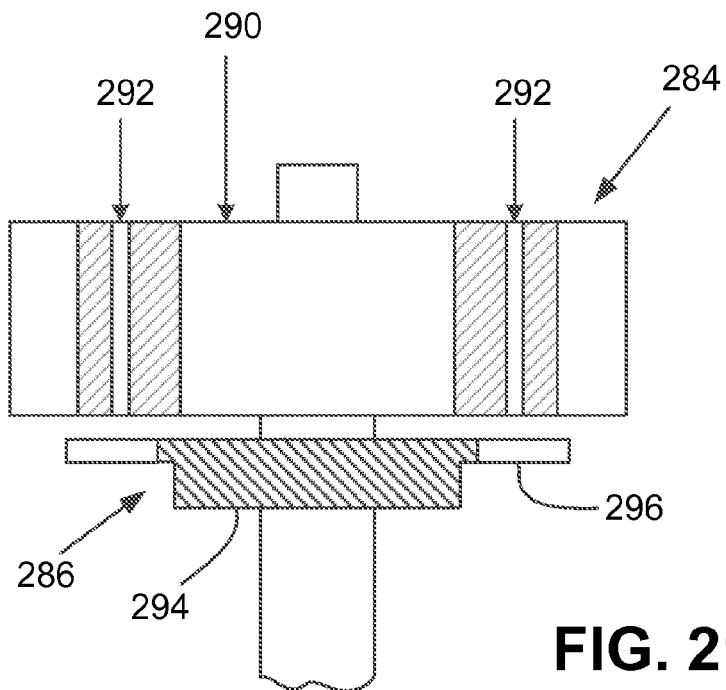


FIG. 21

Section A-A

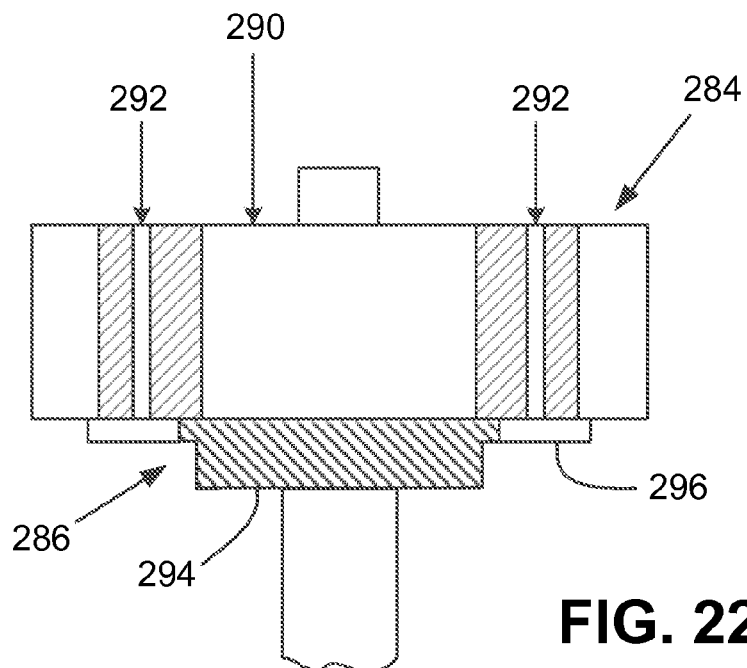


FIG. 22

Section A-A

1

TAP CHANGER HAVING A VACUUM INTERRUPTER ASSEMBLY WITH AN IMPROVED DAMPER

This application is a continuation-in-part application, under 35 U.S.C. §120, of copending PCT Patent Application No. PCT/US2012/030244, having an international filing date of Mar. 23, 2012, which claims the benefit of U.S. Provisional Application No. 61/467,837, filed on Mar. 25, 2011, each of which is hereby incorporated by reference in its entirety.

BACKGROUND OF THE INVENTION

This invention relates to tap changers and more particularly to load tap changers.

As is well known, a transformer converts electricity at one voltage to electricity at another voltage, either of higher or lower value. A transformer achieves this voltage conversion using a primary winding and a secondary winding, each of which are wound on a ferromagnetic core and comprise a number of turns of an electrical conductor. The primary winding is connected to a source of voltage and the secondary winding is connected to a load. Voltage present on the primary winding is induced on the secondary winding by a magnetic flux passing through the core. By changing the ratio of secondary turns to primary turns, the ratio of output to input voltage can be changed, thereby controlling or regulating the output voltage of the transformer. This ratio can be changed by effectively changing the number of turns in the primary winding and/or the number of turns in the secondary winding. This is accomplished by making connections between different connection points or “taps” within the winding(s). A device that can make such selective connections to the taps is referred to as a “tap changer”.

Generally, there are two types of tap changers: on-load tap changers and de-energized or “off-load” tap changers. An off-load tap changer uses a circuit breaker to isolate a transformer from a voltage source and then switches from one tap to another. An on-load tap changer (or simply “load tap changer”) switches the connection between taps while the transformer is connected to the voltage source. A load tap changer may include, for each phase winding, a selector switch assembly, a bypass switch assembly and a vacuum interrupter assembly. The selector switch assembly makes connections to taps of the transformer, while the bypass switch assembly connects the taps, through two branch circuits, to a main power circuit. During a tap change, the vacuum interrupter assembly safely isolates a branch circuit. A drive system moves the selector switch assembly, the bypass switch assembly and the vacuum interrupter assembly. The operation of the selector switch assembly, the bypass switch assembly and the vacuum interrupter assembly are interdependent and carefully choreographed. The present invention is directed toward such a tap changer having a vacuum interrupter assembly with an improved damper.

SUMMARY OF THE INVENTION

In accordance with the present invention, an on-load tap changer is provided having a vacuum interrupter assembly for immersion in a dielectric fluid. The vacuum interrupter assembly includes a vacuum interrupter with contacts. An actuation assembly is provided and includes a shaft connected to the contacts of the vacuum interrupter. The shaft is operable upon movement to open and close the contacts. A damper is operable to dampen the movement of the shaft. The damper includes a housing having a wall with an opening.

2

The housing defines an interior chamber into which the shaft extends. The interior chamber is in communication with the opening. A piston is disposed in the interior chamber and is secured to the shaft so as to be movable therewith. The piston has one or more first openings and one or more second openings. The one or more first openings are larger than the one or more second openings. A blocking structure is disposed in the interior chamber such that the piston is disposed between the opening and the blocking structure. The blocking structure has a body through which the shaft movably extends. The blocking structure is movable between being proximate and distal to the piston, wherein when the blocking structure is proximate to the piston, the blocking structure closes the one or more first openings, but not the one or more second openings, and wherein when the blocking structure is distal to the piston, the blocking structure does not close either the one or more first openings or the one or more second openings. A spring biases the blocking structure toward the piston. During movement of the shaft to close the contacts, the blocking structure is disposed proximate to the piston. When the shaft moves to open the contacts, the blocking structure moves against the bias of the spring to be distal from the piston, thereby opening the one or more first openings.

BRIEF DESCRIPTION OF THE DRAWINGS

The features, aspects, and advantages of the present invention will become better understood with regard to the following description, appended claims, and accompanying drawings where:

FIG. 1 shows a front elevational view of a tap changer of the present invention;

FIG. 2 shows a schematic view of the tap changer;

FIG. 3A shows a circuit diagram of the tap changer in a linear configuration;

FIG. 3B shows a circuit diagram of the tap changer in a plus-minus configuration;

FIG. 3C shows a circuit diagram of the tap changer in a coarse-fine configuration;

FIG. 4 shows a schematic drawing of an electrical circuit of the tap changer;

FIG. 5A shows the electrical circuit in a first stage of a tap change in which a first bypass switch is opened;

FIG. 5B shows the electrical circuit in a second stage of the tap change in which a vacuum interrupter is opened;

FIG. 5C shows the electrical circuit in a third stage of the tap change in which a first contact arm is moved to a new tap;

FIG. 5D shows the electrical circuit in a fourth stage of the tap change in which the vacuum interrupter is closed;

FIG. 5E shows the electrical circuit in a fifth stage of the tap change in which the first bypass switch is closed;

FIG. 6 shows a front view of the interior of a tank of the tap changer;

FIG. 7 shows a rear view of a front support structure of the tap changer;

FIG. 8 shows a front perspective view of the support structure with a bypass switch assembly and a vacuum interrupter assembly mounted thereto;

FIG. 9 shows a plan view of a bypass cam of the bypass switch assembly;

FIG. 10 shows a sectional view of a vacuum interrupter of the vacuum interrupter assembly;

FIG. 11 shows a plan view of a vacuum interrupter cam of the vacuum interrupter assembly;

FIG. 12 shows a perspective view of a shuttle of the vacuum interrupter assembly;

3

FIG. 13 shows a sectional view of a portion of the vacuum interrupter assembly showing the engagement of the shuttle with the vacuum interrupter cam;

FIG. 14 shows a perspective view of a portion of an impact mass of the vacuum interrupter assembly;

FIG. 15 shows a sectional view of a portion of the vacuum interrupter assembly showing the inside of a unidirectional damper;

FIG. 16 shows a perspective view of a piston of the unidirectional damper;

FIG. 17 shows a perspective view of a ring structure of the unidirectional damper;

FIG. 18 shows a front perspective view of the support structure with a second embodiment of the vacuum interrupter assembly mounted thereto;

FIG. 19 shows a cross-sectional view of a portion of the second embodiment of the vacuum interrupter assembly;

FIG. 20 shows a top plan view of a piston, which is disposed above an upper blocking structure;

FIG. 21 shows a sectional view of the piston and the upper blocking structure taken along the line A-A in FIG. 20, wherein the upper blocking structure is disposed distal to the piston; and

FIG. 22 shows a sectional view of the piston and the upper blocking structure taken along the line A-A in FIG. 20, wherein the upper blocking structure is disposed proximate to the piston.

DETAILED DESCRIPTION OF ILLUSTRATIVE EMBODIMENTS

It should be noted that in the detailed description that follows, identical components have the same reference numerals, regardless of whether they are shown in different embodiments of the present invention. It should also be noted that in order to clearly and concisely disclose the present invention, the drawings may not necessarily be to scale and certain features of the invention may be shown in somewhat schematic form.

Referring now to FIGS. 1 and 2, there is shown a load tap changer (LTC) 10 embodied in accordance with the present invention. The LTC 10 is adapted for on-tank mounting to a transformer. Generally, the LTC 10 comprises a tap changing assembly 12, a drive system 14 and a monitoring system 16. The tap changing assembly 12 is enclosed in a tank 18, while the drive system 14 and the monitoring system 16 are enclosed in a housing 20, which may be mounted below the tank 18. The tank 18 defines an inner chamber within which the tap changing assembly 12 is mounted. The inner chamber holds a volume of dielectric fluid sufficient to immerse the tap changing assembly 12. Access to the tap changing assembly 12 is provided through a door 24, which is pivotable between open and closed positions.

The tap changing assembly 12 includes three circuits 30, each of which is operable to change taps on a regulating winding 32 for one phase of the transformer. Each circuit 30 may be utilized in a linear configuration, a plus-minus configuration or a coarse-fine configuration, as shown in FIGS. 3A, 3B, 3C, respectively. In the linear configuration, the voltage across the regulating winding 32 is added to the voltage across a main (low voltage) winding 34. In the plus-minus configuration, the regulating winding 32 is connected to the main winding 34 by a change-over switch 36, which permits the voltage across the regulating winding 32 to be added or subtracted from the voltage across the main winding 34. In the coarse-fine configuration, there is a coarse regulating winding 38 in addition to the (fine) regulating winding 32.

4

A change-over switch 40 connects the (fine) regulating winding 32 to the main winding 34, either directly, or in series, with the coarse regulating winding 38.

Referring now to FIG. 4, there is shown a schematic drawing of one of the electrical circuits 30 of the tap changing assembly 12 connected to the regulating winding 32 in a plus-minus configuration. The electrical circuit 30 is arranged into first and second branch circuits 44, 46 and generally includes a selector switch assembly 48, a bypass switch assembly 50 and a vacuum interrupter assembly 52 comprising a vacuum interrupter 54.

The selector switch assembly 48 comprises movable first and second contact arms 58, 60 and a plurality of stationary contacts 56 which are connected to the taps of the winding 32, respectively. The first and second contact arms 58, 60 are connected to reactors 62, 64, respectively, which reduce the amplitude of the circulating current when the selector switch assembly 48 is bridging two taps. The first contact arm 58 is located in the first branch circuit 44 and the second contact arm 60 is located in the second branch circuit 46. The bypass switch assembly 50 comprises first and second bypass switches 66, 68, with the first bypass switch 66 being located in the first branch circuit 44 and the second bypass switch 68 being located in the second branch circuit 46. Each of the first and second bypass switches 66, 68 is connected between its associated reactor and the main power circuit. The vacuum interrupter 54 is connected between the first and second branch circuits 44, 46 and comprises a fixed contact 164 and a movable contact 166 enclosed in a bottle or housing 168 having a vacuum therein, as is best shown in FIG. 10.

The first and second contact arms 58, 60 of the selector switch assembly 48 can be positioned in a non-bridging position or a bridging position. In a non-bridging position, the first and second contact arms 58, 60 are connected to a single one of a plurality of taps on the winding 32 of the transformer. In a bridging position, the first contact arm 58 is connected to one of the taps and the second contact arm 60 is connected to another, adjacent one of the taps.

In FIG. 4, the first and second contact arms 58, 60 are both connected to tap 4 of the winding 32, i.e., the first and second contact arms 58, 60 are in a non-bridging position. In a steady state condition, the contacts 164, 166 of the vacuum interrupter 54 are closed and the contacts in each of the first and second bypass switches 66, 68 are closed. The load current flows through the first and second contact arms 58, 60 and the first and second bypass switches 66, 68. Substantially no current flows through the vacuum interrupter 54 and there is no circulating current in the reactor circuit.

A tap change in which the first and second contact arms 58, 60 are moved to a bridging position will now be described with reference to FIGS. 5A-5E. The first bypass switch 66 is first opened (as shown in FIG. 5A), which causes current to flow through the vacuum interrupter 54 from the first contact arm 58 and the reactor 62. The vacuum interrupter 54 is then opened to isolate the first branch circuit 44 (as shown in FIG. 5B). This allows the first contact arm 58 to next be moved to tap 5 without arcing (as shown in FIG. 5C). After this move, the vacuum interrupter 54 is first closed (as shown in FIG. 5D) and then the first bypass switch 66 is closed (as shown in FIG. 5E). This completes the tap change. At this point, the first contact arm 58 is connected to tap 5 and the second contact arm 60 is connected to tap 4, i.e., the first and second contact arms 58, 60 are in a bridging position. In a steady state condition, the contacts 164, 166 of the vacuum interrupter 54 are closed and the contacts in each of the first and second bypass switches 66, 68 are closed. The reactors 62, 64 are now

5

connected in series and the voltage at their midpoint is one half of the voltage per tap selection. Circulating current now flows in the reactor circuit.

Another tap change may be made to move the second contact arm 60 to tap 5 so that the first and second contact arms 58, 60 are on the same tap (tap 5), i.e., to be in a non-bridging position. To do so, the above-described routine is performed for the second branch circuit 46, i.e., the second bypass switch 68 is first opened, then the vacuum interrupter 54 is opened, the second contact arm 60 is moved to tap 5, the vacuum interrupter 54 is first closed and then the second bypass switch 68 is closed.

In the tap changes described above, current flows continuously during the tap changes, while the first and second contact arms 58, 60 are moved in the absence of current.

As best shown in FIG. 4, the selector switch assembly 48 may have eight stationary contacts 56 connected to eight taps on the winding 32 and one stationary contact 56 connected to a neutral (mid-range) tap of the winding 32. Thus, with the change-over switch 36 on the B terminal (as shown), the selector switch assembly 48 is movable among a neutral position and sixteen discreet raise (plus) positions (i.e., eight non-bridging positions and eight bridging positions). With the change-over switch 36 on the A terminal, the selector switch assembly 48 is movable among a neutral position and sixteen discreet lower (minus) positions (i.e., eight non-bridging positions and eight bridging positions). Accordingly, the selector switch assembly 48 is movable among a total of 33 positions (one neutral position, 16 raise (R) positions and 16 lower (L) positions).

Referring now to FIG. 6, three support structures 80 are mounted inside the tank 18, one for each electrical circuit 30. The support structures 80 are composed of a rigid, dielectric material, such as fiber-reinforced dielectric plastic. For each electrical circuit 30, the bypass switch assembly 50 and the vacuum interrupter assembly 52 are mounted on a first (or front) side of a support structure 80, while the selector switch assembly 48 is mounted behind the support structure 80.

Referring now to FIG. 7, the bypass switch assembly 50 includes a bypass gear 82 connected by an insulated shaft 83 to a transmission system, which, in turn, is connected to an electric motor. The bypass gear 82 is fixed to a bypass shaft that extends through the support structure 80 and into the first side of the support structure 80. The bypass gear 82 is connected by a chain 90 to a vacuum interrupter (VI) gear 92 secured on a VI shaft 94. The VI shaft 94 also extends through the support structure 80 and into the first side of the support structure 80. When the motor is activated to effect a tap change, the transmission system and the shaft 83 convey the rotation of a shaft of the motor to the bypass gear 82, thereby causing the bypass gear 82 and the bypass shaft to rotate. The rotation of the bypass gear 82, in turn, is conveyed by the chain 90 to the VI gear 92, which causes the VI gear 92 and the VI shaft 94 to rotate.

On the first side of the support structure 80, the bypass shaft is secured to a bypass cam 100, while the VI shaft 94 is secured to a VI cam 102. The bypass cam 100 rotates with the rotation of the bypass shaft and the VI cam 102 rotates with the rotation of the VI shaft 94. As will be described in more detail below, the bypass and VI gears 82, 92 are sized and arranged to rotate the bypass cam 100 through 180 degrees for each tap change and to rotate the VI cam 102 through 360 degrees for each tap change.

Referring now to FIG. 8, the bypass switch assembly 50 includes the first and second bypass switches 66, 68, the bypass shaft and the bypass cam 100, as described above. Each of the first and second bypass switches 66, 68 comprises

6

a plurality of contacts 104 arranged in a stack and held in a contact carrier 106. The contacts 104 are composed of a conductive metal, such as copper. Each contact 104 has a first or inner end and a second or outer end. A tapered notch (with a gradual V-shape) is formed in each contact 104 at the outer end, while a mounting opening extends through each contact 104 at the inner end. In each of the first and second contact switches 66, 68, when the contacts 104 are arranged in a stack, the tapered notches align to form a tapered groove. In addition, the mounting openings align to form a mounting bore extending through the switch. Each of the first and second bypass switches 66, 68 is pivotally mounted to the support structure 80 by a post 114 that extends through the mounting bore in the contacts 104, as well as aligned holes in the contact carrier 106 and a major tie bar 116 that extends between the first and second bypass switches 66, 68. The major tie bar 116 has been partially removed in FIG. 8 to better show other features. The entire major tie bar 116 can be seen in FIG. 6.

Each of the first and second bypass switches 66, 68 is movable between a closed position and an open position. In the closed position, a fixed contact post 118 is disposed in the groove and is in firm contact with the contacts 104. In the open position, the fixed contact post 118 is not disposed in the groove and the contacts 104 are spaced from the fixed contact post 118. The fixed contact posts 118 are both electrically connected to the main power circuit and, more specifically, to a neutral terminal. Each of the first and second bypass switches 66, 68 is moved between the closed and open positions by an actuation assembly 120.

The actuation assembly 120 is part of the bypass switch assembly 50 and comprises first and second bell cranks 122, 124. Each of the first and second bell cranks 122, 124 has a main connection point, a linkage connection point and a follower connection point, which are arranged in the configuration of a right triangle, with the main connection point being located at the right angle vertex. The first and second bell cranks 122, 124 are pivotally connected at their main connection points to the support structure by posts 126, respectively. The posts 126 extend through openings in the first and second bell cranks 122, 124 at the main connection points and through openings in the ends of a minor tie bar 130. A first end of a pivotable first linkage 132 is connected to the linkage connection point of the first bell crank 122 and a second end of the pivotable first linkage 132 is connected to the contact carrier 106 of the first bypass switch 66. Similarly, a first end of a pivotable second linkage 134 is connected to the linkage connection point of the second bell crank 124 and a second end of the pivotable second linkage 134 is connected to the contact carrier 106 of the second bypass switch 68. A wheel-shaped first cam follower 136 is rotatably connected to the follower connection point of the first bell crank 122, while a wheel-shaped second cam follower 138 is rotatably connected to the follower connection point of the second bell crank 124.

Referring now also to FIG. 9, the bypass cam 100 is generally circular and has opposing first and second major surfaces. A pair of enlarged indentations 140 may be formed in a peripheral surface of the bypass cam 100. The indentations 140 are located on opposing sides of the bypass cam 100 and have a nadir. The second major surface is flat and is disposed toward the support structure 80. The first major surface is disposed toward the door 24 (when it is closed) and has an endless, irregular groove 142 formed therein. The groove 142 is partly defined by a central area 144 having arcuate major and minor portions 148, 150. The major portion 148 has a greater radius than the minor portion 150. The transitions between the major and minor portions are tapered.

7

The first and second cam followers **136**, **138** are disposed in the groove **142** on opposite sides of the central area **144**. In a neutral or home position, the minor portion **150** of the bypass cam **100** is disposed toward the vacuum interrupter assembly **52**, while the major portion **148** of the bypass cam **100** is disposed away from the vacuum interrupter assembly **52**. In addition, the first and second cam followers **136**, **138** are both in contact with the minor portion **150** at the junctures with the transitions to the major portion **148**, respectively. With the first and second cam followers **136**, **138** in these positions, both of the first and second bypass switches **66**, **68** are in the closed position. When the bypass cam **100** is in the home position, the first and second contact arms **58**, **60** are in a non-bridging position.

FIG. **8** shows the bypass cam **100** after it has rotated clockwise from its home, or neutral position in response to the initiation of a tap change. This rotation causes the first cam follower **136** to move (relatively speaking) through the transition and into contact with the major portion **148**, while the second cam follower **138** simply travels over the minor portion **150**. The movement of the first cam follower **136** through the transition increases the radius of the central area in contact with the first cam follower **136**, thereby moving the first cam follower **136** outward. This outward movement, in turn, causes the first bell crank **122** to pivot counter-clockwise about the main connection point. This pivoting movement causes the first linkage **132** to pull the first bypass switch **66** outward, away from the fixed contact post **118**, to the open position. As the first cam follower **136** moves over the major portion **148**, the first bypass switch **66** is maintained in the open position. As the bypass cam **100** continues to rotate, the first cam follower **136** moves over the transition to the minor portion **150**, thereby decreasing the radius of the central area **144** in contact with the first cam follower **136**, which allows the first cam follower **136** to move inward and the first bell crank **122** to pivot clockwise. This pivoting movement causes the first linkage **132** to push the first bypass switch **66** inward, toward the fixed contact post **118**, to the closed position. At this point, the tap change is complete and the bypass cam **100** has rotated **180** degrees to an intermediate position. The first and second cam followers **136**, **138** are again both in contact with the minor portion **150** at the junctures with the transitions to the major portion **148**, respectively, but the major portion **148** of the bypass cam **100** is now disposed toward the vacuum interrupter assembly **52**, while the minor portion **150** of the bypass cam **100** is disposed away from the vacuum interrupter assembly **52**. With the bypass cam **100** in this, intermediate position, both of the first and second bypass switches **66**, **68** are again in the closed position. In addition, the first and second contact arms **58**, **60** are in a bridging position.

If another tap change is made so that the second contact arm **60** is moved to the same tap as the first contact arm **58**, i.e., a non-bridging position, the bypass cam **100** again rotates in the clock-wise direction, the second cam follower **138** moves through the transition and into contact with the major portion **148**, while the first cam follower **136** simply travels over the minor portion **150**. The movement of the second cam follower **138** through the transition increases the radius of the central area **144** in contact with the second cam follower **138**, thereby moving the second cam follower **138** outward. This outward movement, in turn, causes the second bell crank **124** to pivot clockwise about the main connection point. This pivoting movement causes the second linkage **134** to pull the second bypass switch **68** outward, away from the fixed contact post **118**, to the open position. As the second cam follower **138** moves over the major portion **148**, the second

8

bypass switch **68** is maintained in the open position. As the bypass cam **100** continues to rotate, the second cam follower **138** moves over the transition to the minor portion **150**, thereby decreasing the radius of the central area **144** in contact with the second cam follower **138**, which allows the second cam follower **138** to move inward and the second bell crank **124** to pivot counter-clockwise. This pivoting movement causes the second linkage **134** to push the second bypass switch **68** inward, toward the fixed contact post **118**, to the closed position. At this point, the bypass cam **100** has rotated **360** degrees and the bypass cam **100** is back in the home position.

A pair of follower arms **152** may optionally be provided. The follower arms **152** are pivotally mounted to the support structure **80** and have rollers rotatably mounted to outer ends thereof, respectively. A spring **156** biases the outer ends of the follower arms **152** towards each other. This bias causes the rollers at the end of a tap change to move into the nadirs in the indentations **140**. In this manner, the follower arms **152** are operable to bias the bypass cam **100** toward the home position and the intermediate position at the end of a tap change.

Referring now also to FIG. **10**, the vacuum interrupter assembly **52** generally comprises the vacuum interrupter **54** and an actuation assembly **160**.

The vacuum interrupter **54** is supported on and secured to a mount **162** that is fastened to the support structure **80**. The vacuum interrupter **54** generally includes a fixed contact **164** and a movable contact **166** disposed inside a sealed bottle or housing **168**. The housing **168** comprises a substantially cylindrical sidewall secured between upper and lower end cups so as to form a hermetically sealed inner chamber, which is evacuated to about 10^{-5} Torr. The sidewall is composed of an insulating material such as a high-alumina ceramic material, a glass material or a porcelain material. The fixed and movable contacts **164**, **166** are disc-shaped and may be of the butt-type. When the fixed and movable contacts **164**, **166** are contacted together, they permit current to flow through the vacuum interrupter **54**. The fixed contact **164** is electrically connected to a fixed electrode **172**, which is secured to and extends through the lower end cup of the housing **168**. The fixed electrode **172** is electrically connected to the mount **162**, which, in turn, is electrically connected to the first branch circuit **44**. The movable contact **166** is electrically connected to a movable electrode **174**, which extends through the upper end cup of the housing **168** and is movable along a longitudinal axis relative to the fixed electrode **172**. Upward movement of the movable electrode **174** opens the contacts **164**, **166**, while downward movement of the movable electrode **174** closes the contacts **164**, **166**. The relative motion of the movable electrode **174** is accomplished via a metal bellows structure **176**, which is attached at one of its ends to the movable electrode **174** and at the other of its ends to the upper end cup.

A flexible metal strap **178** electrically connects the movable electrode **174** of the vacuum interrupter **54** to a bus bar of the second branch circuit **46**. The metal strap **178** may be comprised of braided strands of wire. The metal strap **178** is secured to the movable electrode **174** by a swivel **180**, which extends through a hole in an electrode of the metal strap **178** and is threadably received in a threaded bore of the movable electrode **174**. A lower end of an interrupter shaft **182** is connected to the swivel **180** by a shoulder bolt. An upper end of the interrupter shaft **182** is threadably connected to a damper shaft **186**. The swivel **180**, the interrupter shaft **182** and the damper shaft **186** cooperate to form an actuation shaft **188**.

A dielectric shield **330** may be mounted to the bus bar of the second branch circuit **46**, as shown in FIG. **18**. The dielectric shield **330** extends over the metal strap **178** so as to be disposed between the metal strap **178** and the door **24**. The dielectric shield **330** is composed of a conductive material, such as steel, and is at the same potential as the metal strap **178**. Without the dielectric shield **330**, if the metal strap **178** is damaged such that a strand of wire extends outward, toward the door **24**, a very high magnitude electric field may be created at the loose end of the strand. Since the dielectric shield **330** is at the same potential as the metal strap **178**, the dielectric shield reduces the magnitude of the electric field to a very low level.

The actuation assembly **160** generally comprises the VI cam **102**, the actuation shaft **188**, a shuttle **190**, an impact mass **192**, a unidirectional damper **194** and a contact erosion damper **196**. Both the shuttle **190** and the impact mass **192** may be composed of metal, such as steel. The impact mass **192**, however, is significantly heavier (has more mass) than the shuttle **190**.

Referring now to FIG. **11**, there is shown a front view of the VI cam **102**. As shown, the VI cam **102** is substantially circular and has opposing first and second major surfaces. The second major surface is flat and is disposed toward the support structure **80**. The first major surface is disposed toward the door **24** and has an endless, irregular groove **202** formed therein. The groove **202** is partly defined by a central area **204** having arcuate major and minor portions **206**, **208**. The major portion **206** has a greater radius than the minor portion **208**. The transitions between the major and minor portions **206**, **208** are tapered. A hole **210** extends through the VI cam **102** inside the groove **202** and is disposed at the center of the major portion **206**.

Referring back to FIG. **8**, upper and lower rail mounts **214**, **216** are secured to the support structure **80** and are disposed above and below the VI cam **102**, respectively. The upper rail mount **214** has a box-shaped central structure **218**, and the lower rail mount **216** has a box-shaped central structure **220**. Outer portions of the upper rail mount **214** hold upper ends of a pair of rails **222**, while outer portions of the lower rail mount **216** hold lower ends of the rails **222**. The rails **222** extend between the upper and lower rail mounts **214**, **216** and bracket the VI cam **102**. In this manner, the upper and lower rail mounts **214**, **216** and the rails **222** surround the VI cam **102**.

The shuttle **190** is disposed over the VI cam **102**. A second side of the shuttle **190** is disposed toward the VI cam **102**, while a first side of the shuttle **190** is disposed toward the door **24** (when it is closed). The shuttle **190** is mounted to the rails **222** and is movable between the upper and lower rail mounts **214**, **216**. As shown in FIG. **12**, the shuttle **190** has a rectangular body **224** with an enlarged central opening **226** disposed between a pair of upper openings **228** and a pair of lower openings **230**. A pawl release plate **232** is secured in each of the upper and lower openings **228**, **230**. A cylindrical upper guide **234** and a cylindrical lower guide **236** are joined to each side of the body **224**, with the upper guides **234** being located at the top of the body **224** and the lower guides **236** being located at the bottom of the body **224**. Each of the upper and lower guides **234**, **236** has a central bore extending therethrough. On each side of the shuttle **190**, one of the rails **222** extends through the upper and lower guides **234**, **236**.

Referring now to FIG. **13**, a cam follower **238** is rotatably secured to the body **224** and projects from the second side of the shuttle **190**. The cam follower **238** is disposed in the groove **202** of the VI cam **102**. In a neutral or home position, the minor portion **208** of the VI cam **102** is disposed upward, while the major portion **206** of the VI cam **102** is disposed

downward and the hole **210** is also disposed at its lowermost position. In addition, the cam follower **238** is in contact with the center of the minor portion **208**. With the cam follower **238** in this position, the shuttle **190** is in its lowermost position and the contacts **164**, **166** of the vacuum interrupter **54** are closed.

When the VI cam **102** is in the home position and a tap change is initiated, the VI cam **102** starts to rotate in a clockwise direction as viewed in FIG. **8**. This rotation causes the cam follower **238** to move over half of the minor portion **208**, through the transition and into contact with the major portion **206**. The movement of the cam follower **238** through the transition increases the radius of the central area **204** in contact with the cam follower **238**, thereby moving the cam follower **238** upward. This upward movement, in turn, causes the shuttle **190** to move upward to an uppermost position. As will be described more fully below, the upward movement of the shuttle **190** to the uppermost position causes the contacts **164**, **166** of the vacuum interrupter **54** to open. As the cam follower **238** moves over the major portion **206**, the shuttle **190** is maintained in the uppermost position (and the contacts **164**, **166** of the vacuum interrupter **54** remain open). As the VI cam **102** continues to rotate, the cam follower **238** moves over the transition to the minor portion **208**, thereby decreasing the radius of the central area **204** in contact with the cam follower **238**, which allows the cam follower **238** and, thus the shuttle **190**, to move downward. As will be described more fully below, the downward movement of the shuttle **190** to the lowermost or home position causes the contacts **164**, **166** of the vacuum interrupter **54** to close. At this point, the tap change is complete and the VI cam **102** has rotated **360** degrees back to its home position.

Referring now to FIG. **8** and FIG. **14**, the impact mass **192** is generally H-shaped and is comprised of a central structure **240** secured between a pair of outer plates **242** by screws or other fastening means. As best shown in FIG. **14**, the central structure **240** is also H-shaped and includes a pair of enlarged outer blocks **244** connected to a smaller center block **246**. A smooth bore extends through each outer block **244**, between upper and lower faces of the outer block **244**. The center block **246** also has a smooth bore extending therethrough, between upper and lower faces of the center block **246**. A channel **248** is formed in a front face of the center block **246**. A channel **248** is also formed in a rear face of the center block **246**.

An erosion gap cylinder **250** is secured to the upper face of the center block **246**. The erosion gap cylinder **250** is part of the contact erosion damper **196** and defines an interior space. The erosion gap cylinder **250** may be integrally joined to a plate **252** that is secured by screws or other fastening means to the center block **246**. The erosion gap cylinder **250** has an open upper end and a lower end wall with an opening therein. The open upper end and the opening in the lower end wall are aligned with the bore in the center block **246**. A notch **254** is formed in a side wall of the erosion gap cylinder **250**. The notch **254** has a decreasing width from top to bottom. In the embodiment shown in FIG. **14**, the notch **254** extends from an upper rim of the erosion gap cylinder **250** down to just above the plate **252** (e.g. about half a millimeter) and is substantially wedge-shaped. The erosion gap cylinder **250** (and its interior space) have a slightly inverted, frusto-conical shape, with a larger diameter at the upper rim than at the juncture with the plate **252**.

The impact mass **192** is enmeshed with, but movable relative to, the shuttle **190**. A portion of the center block **246** of the impact mass **192** is disposed in the central opening **226** of the body of the shuttle **190**. On each side of the body of the shuttle **190**, a corresponding outer block **244** is vertically disposed

11

between the guides **234**, **236** and is positioned such that its bore is aligned with the bore in the guides **234**, **236**. In this manner, the rails **222** extend through the outer blocks **244** of the impact mass **192**, as well as the guides **234**, **236** of the shuttle **190**. As will be described more fully below, the impact mass **192** moves with the shuttle **190**.

A pair of helical upper springs **258** are fastened between upper surfaces of the outer blocks **244** of the impact mass **192** and the upper guides **234** of the shuttle **190**, respectively, with the rails **222** extending through the upper springs **258**. A pair of lower springs **260** are fastened between lower surfaces of the outer blocks **244** of the impact mass **192** and the lower guides **236** of the shuttle **190**, respectively, with the rails **222** extending through the lower springs **260**.

Referring now to FIGS. **8** and **13**, a pair of spaced-apart pawl rails **261** extend between the upper and lower rail mounts **214**, **216**. Upper ends of the pawl rails **261** are secured to opposing side walls of the central structure **218** of the upper rail mount **214**, respectively, while lower ends of the pawl rails **261** are secured to opposing side walls of the central structure **220** of the lower rail mount **216**, respectively. An upper pawl **262** and a lower pawl **264** are pivotally mounted between the pawl rails **261**. Each of the upper and lower pawls **262**, **264** has a catch end and an opposing release end. The catch ends **266** face each other, with the upper pawl **262** being disposed above the lower pawl **264**. Each of the upper and lower pawls **262**, **264** is pivotable between an engaged position, wherein the catch end is disposed in the channel **248** of the impact mass **192**, and a disengaged position, wherein the catch end is disposed outward from the channel **248** of the impact mass **192**. Springs **270** are connected between the upper and lower pawls **262**, **264** and the pawl rails **261**, respectively, and are operable to bias the upper and lower pawls **262**, **264** toward their engaged positions. The springs **270** may be helical springs or leaf springs, as shown. When the shuttle **190** is in the home position, the lower pawl **264** is in the engaged position and the upper pawl **262** is in the disengaged position. When the shuttle **190** is in the uppermost position, the upper pawl **262** is in the engaged position and the lower pawl **264** is in the disengaged position.

With quick reference to FIGS. **18** and **19**, there is shown another embodiment of the present invention having a vacuum interrupter assembly **52'** with the same construction as the vacuum interrupter assembly **52**, except the upper and lower pawls **262**, **264** are biased by spring-loaded plungers **320** instead of the springs **270**. The spring-loaded plungers **320** are mounted in a housing **322** that is secured between the pawl rails **261**. The spring-loaded plungers **320** are operable to bias the upper and lower pawls **262**, **264** toward their engaged positions.

With reference now to FIG. **14**, the interrupter shaft **182** extends upward from the swivel **180** and passes through the bore of the center block **246** of the impact mass **192**. Below the center block **246**, a middle spring **274** is disposed around the interrupter shaft **182**. The middle spring **274** is helical and is trapped between a plate secured to the lower face of the center block **246** and a flange **276** secured to the interrupter shaft **182**. Above the center block **246**, an erosion gap piston **278** is secured to the interrupter shaft **182**. The erosion gap piston **278** is cylindrical and extends out radially from the interrupter shaft **182**. When the contacts **164**, **166** are closed, a lower portion of the erosion gap piston **278** is disposed inside the erosion gap cylinder **250** secured to the center block **246**, while an upper portion of the erosion gap piston **278** is disposed above the erosion gap cylinder **250**. In this regard, it should be noted that in FIG. **14**, the entire erosion gap piston **278** is shown being located above the erosion gap cylinder

12

250. This is done only for purposes of showing the components better. With the erosion gap piston **278** partially disposed in the erosion gap cylinder **250**, an erosion gap is defined between a bottom surface of the erosion gap piston **278** and the lower end wall of the erosion gap cylinder **250**. The erosion gap piston **278** and the erosion gap cylinder **250** cooperate to form the contact erosion damper **196**.

Above the erosion gap piston **278**, the interrupter shaft **182** is threadably secured to the damper shaft **186**, which extends upward, into the central structure **218** of the upper rail mount **214**. The central structure **218** forms a part of the unidirectional damper **194**. With reference now to FIG. **15**, there is shown a sectional view of the central structure **218**. A cylindrical bore or chamber **282** is formed inside the central structure **218**. A piston **284** and a pair of blocking structures **286** are disposed inside the chamber **282**. The piston **284** is secured to an upper portion of the damper shaft **186** and is moveable therewith. As shown in FIG. **16**, the piston **284** is cylindrical and has a central bore in which the damper shaft **186** is fixedly disposed. A plurality of enlarged kidney-shaped openings **290** extend through the piston **284** and are arranged in a circular configuration, around the central bore. A plurality of smaller, circular openings **292** also extend through the piston **284** and are arranged radially outward from the kidney-shaped openings **290**. In the embodiment shown in FIG. **16**, there are four kidney-shaped openings **290** and four circular openings **292**. As will be discussed more fully below, the size and number of the kidney-shaped openings **290** and the circular openings **292** help determine the damping characteristics of the unidirectional damper **194**. It should be appreciated that the openings **290**, **292** may have different shapes without departing from the scope of the present invention.

As shown in FIG. **17**, the blocking structures **286** each have a cylindrical body **294** with an axial bore through which the damper shaft **186** extends. An annular flange **296** is joined to the body **294** of the blocking structure **286**. Both of the blocking structures **286** are movable along the damper shaft **186**. A helical spring **300** is disposed around the damper shaft **186** and the bodies **294** of the blocking structures **286**. The spring **300** biases the upper one of the blocking structures **286** toward a closing position, wherein the flange **296** abuts the bottom surface of the piston **284**. When the flange **296** of the upper blocking structure **286** abuts the bottom surface of the piston **284**, the flange **296** blocks the kidney-shaped openings **290**. The circular openings **292**, however, are unblocked. As will become apparent from the description below, the blocking structures **286** and the spring **300** function as a one-way check valve.

The operation of the actuation assembly will now be described. When a tap change is being made, the contacts **164**, **166** of the vacuum interrupter **54** are first opened and then closed, as described above. This opening and closing is accomplished by the 360° degree rotation of the VI cam **102**, which first moves the cam follower **238** and, thus, the shuttle **190** to the uppermost position and then allows the cam follower **238** and, thus the shuttle **190**, to move downward to the home position, also as described above.

As the shuttle **190** moves upward to the uppermost position, the middle spring **274** and the upper and lower springs **258**, **260** cause the impact mass **192** to try to follow the shuttle **190**. The lower pawl **264**, however, which is in the engaged position, prevents the impact mass **192** from following the shuttle **190**. As a result, the lower springs **260** compress (storing compression forces) and the upper springs **258** extend. In addition, the middle spring **274** is compressed (storing compression force). When the pawl release plates

13

232 in the lower openings 230 of the shuttle 190 contact the release end of the lower pawl 264, they pivot the lower pawl 264 so as to move to the disengaged position, thereby releasing the impact mass 192 and all of the stored forces. The released forces cause the impact mass 192 to snap upward. As the impact mass 192 moves upward, the lower end wall of the erosion gap cylinder 250 moves up the distance of the erosion gap (i.e., eliminates the erosion gap) and contacts the erosion gap piston 278 secured to the interrupter shaft 182, thereby causing the interrupter shaft 182 to move upward. The impact mass 192 continues to move upward until it overshoots the upper pawl 262, rebounds downward and then is caught by the upper pawl 262. The upward movement of the interrupter shaft 182 moves the movable electrode 174 upward, which, in turn, opens the contacts 164, 166 of the vacuum interrupter 54. Since the stored forces of the middle spring 274 and the lower springs 260 cause the impact mass 192 to snap upward, an initially high upward force is applied to the movable contact 166, which helps break any welds that may have formed between the closed contacts 164, 166.

The upward movement of the impact mass 192 that occurs before the elimination of the erosion gap causes the middle spring 274 to extend. After the elimination of the erosion gap, the middle spring 274 stops extending. At this point, although the middle spring 274 is extended, it still stores a compression force, i.e., a pre-load.

As the shuttle 190 moves downward toward the home position, the upper and lower springs 258, 260 cause the impact mass 192 to try to follow the shuttle 190. The upper pawl 262, however, which is in the engaged position, prevents the impact mass 192 from following the shuttle 190. As a result, the upper springs 258 compress (storing compression forces) and the lower springs 260 extend. When the pawl release plates 232 in the upper openings 228 of the shuttle 190 contact the release end of the upper pawl 262, they pivot the upper pawl 262 so as to move to the disengaged position, thereby releasing the impact mass 192 and all of the stored forces. The released forces cause the impact mass 192 to snap downward. The downward movement of the impact mass 192 is conveyed through the middle spring 274 to the interrupter shaft 182 via the flange 276, causing the interrupter shaft 182 to move downward. The impact mass 192 continues to move downward until it overshoots the lower pawl 264, rebounds upward and then is caught by the lower pawl 264. The downward movement of the interrupter shaft 182 moves the movable electrode 174 downward, which, in turn, causes the contacts 164, 166 of the vacuum interrupter 54 to close.

During closing, when the contacts 164, 166 of the vacuum interrupter 54 impact against each other, the pre-load in the middle spring 274 is applied very rapidly to the closed contacts 164, 166 in a very short displacement of the impact mass 192. As the impact mass 192 continues moving downward, the middle spring 274 is further compressed, thereby bringing a small additional force to bear on the contacts 164, 166. The middle spring 274 reaches its highest compression as the asymmetry in the current peaks. This yields the highest possible spring force at the moment when the current with its corresponding blow-open force peaks. This fully compressed state occurs when the impact mass 192 is at the maximum downward overshoot of the lower pawl 264. When the impact mass 192 rebounds, the middle spring 274 extends a bit from its fully compressed position until the lower pawl 264 stops the travel of the impact mass 192. The middle spring 274, however, still provides a compression force that is applied to the closed contacts 164, 166 in this latched position. This force is in addition to the force resulting from the pressure differential across the bellows structure 176 of the vacuum

14

interrupter 54. The additional force of the middle spring 274 helps keep the contacts 164, 166 closed during a short-circuit event. The spring force is also beneficial if a dehydrating breather gets clogged and the pressure in the tank 18 drops as a result. In that scenario the contact force resulting from the pressure differential across the bellows structure 176 will be reduced by the reduction in the pressure differential itself.

In the foregoing operation of the actuation assembly, it is important that the actuation shaft 188 move in a manner that does not damage the bellows structure 176 of the vacuum interrupter 54. In addition, the actuation shaft 188 must, on its upward or opening movement, start brusquely to separate the contacts 164, 166 (which may be welded together), but must on its downward or closing movement, travel relatively gently to avoid over-travel and damage to the vacuum interrupter 54. The unidirectional damper 194 helps achieve this carefully controlled movement. More specifically, the movement of the piston 284 (which is attached to the damper shaft 186) through dielectric fluid in the chamber 282 creates resistance (damping) that slows the movement of the actuation shaft 188. This resistance is much greater during the downward movement of the actuation shaft 188 (closing of the contacts 164, 166) than the upward movement of the actuation shaft 188 (opening of the contacts 164, 166).

When the actuation shaft 188 moves upward during the opening of the contacts 164, 166, the pressure above the piston 284 is greater than the pressure below the piston 284, which creates an opening pressure differential across the flange 296 of the upper blocking structure 286. This opening pressure differential, coupled with the inertia of the upper blocking structure 286 and its tendency to stay where it is, overcomes the bias of the spring 300 and deflects the flange 296 of the upper blocking structure 286 away from the piston 284, thereby opening the kidney-shaped openings 290 in the piston 284 and allowing dielectric fluid to pass through the kidney-shaped openings 290, as shown in FIG. 21. Since the kidney-shaped openings 290 are large and allow dielectric fluid to pass facily therethrough, they significantly reduce the resistance of the piston 284 moving through the dielectric fluid in the chamber 282, i.e., the damping effect of the piston 284 is small.

When the actuation shaft 188 moves downward during the closing of the contacts 164, 166, the pressure above the piston 284 is less than the pressure below the piston 284, which creates a closing pressure differential across the flange 296 of the upper blocking structure 286. This closing pressure differential, coupled with the bias of the spring 300, keeps the flange 296 of the upper blocking structure 286 pressed against the piston 284, which keeps the kidney-shaped openings 290 closed, as shown in FIG. 22. Thus, dielectric fluid can only pass through the piston 284 via the small circular openings 292. As a result, there is significant resistance against the movement of the piston 284 through the dielectric fluid in the chamber 282, i.e., the damping effect of the piston 284 is large.

In addition to the unidirectional damper 194, the contact erosion damper 196 also modifies the movement of the actuation shaft 188. More specifically, the erosion damper 196 modifies the movement of the actuation shaft 188 to account for erosion of the contacts 164, 166. As the contacts 164, 166 erode, the position at which the contacts 164, 166 impact, within the vacuum interrupter 54, moves closer to the bottom of the vacuum interrupter 54. The contact erosion is approximately equal on both of the contacts 164, 166. Since, the bottom end of the vacuum interrupter 54 is fixed in its position, the point of interface between the two contacts 164, 166 moves downward as the contacts 164, 166 erode. Thus, for the

15

same uppermost position of the actuation shaft **188**, the upward travel distance of the actuation shaft **188** increases as the contacts **164**, **166** erode due to a lower starting point. The contact erosion damper **196** permits the fixed travel distance of the impact mass **192** to accommodate this change in travel distance of the actuation shaft **188**. As described above, an erosion gap is formed between the lower end wall of the erosion gap cylinder **250** and the erosion gap piston **278** when the contacts **164**, **166** are closed. This erosion gap becomes smaller as the contacts **164**, **166** erode because the actuation shaft **188** and the erosion gap piston **278** progressively move downward, toward the erosion gap cylinder **250**, as the contacts **164**, **166** erode due to the point of interface between the contacts **164**, **166** moving downward. Since the erosion gap becomes smaller, the erosion gap cylinder **250** contacts the erosion gap piston **278** sooner as the contacts **164**, **166** erode. Thus, the impact mass **192** moves the actuation shaft **188** sooner as the contacts **164**, **166** erode, which permits the impact mass **192** to move the actuation shaft **188** farther during its travel.

The configuration of the erosion gap cylinder **250** and the progressively decreasing size of the notch **254** in the erosion gap cylinder **250** help extend the life of the vacuum interrupter **54**. The larger diameter of the erosion gap cylinder **250** and the larger width of the notch **254** toward the top of the erosion gap cylinder **250** permit dielectric fluid to readily escape the erosion gap cylinder **250** as the erosion gap cylinder **250** initially starts to move upward, toward the erosion gap piston **278**. This prevents the dielectric fluid in the erosion gap cylinder **250** from compressing, which keeps the initial relative motion between the erosion gap piston **278** and erosion gap cylinder **250** from opening the contacts **164**, **166** prematurely with an inadequate speed. As the position of the bottom of the erosion gap piston **278** relative to the erosion gap cylinder **250** arrives at the bottom of the notch **254**, the dielectric fluid remaining in the erosion gap cylinder **250** becomes compressed. Without in any way intending to limit the scope of the present invention or being limited to any particular theory, it is believed that the force from this compression of the dielectric fluid may eliminate clearances of loose parts within the actuation shaft **188**, such as at the shoulder bolt connecting the interrupter shaft **182** to the swivel **180**. Also, dielectric fluid trapped between the bottom of the erosion gap piston **278** and the lower end wall of the erosion gap cylinder **250** may act as a shock absorber between the erosion gap cylinder **250** and erosion gap piston **278**.

It is to be understood that the description of the foregoing exemplary embodiment(s) is (are) intended to be only illustrative, rather than exhaustive, of the present invention. Those of ordinary skill will be able to make certain additions, deletions, and/or modifications to the embodiment(s) of the disclosed subject matter without departing from the spirit of the invention or its scope, as defined by the appended claims.

What is claimed is:

1. An on-load tap changer, comprising:
 - a vacuum interrupter assembly for immersion in a dielectric fluid, the vacuum interrupter assembly comprising:
 - (a.) a vacuum interrupter with contacts;
 - (b.) an actuation assembly having a shaft connected to the contacts of the vacuum interrupter and operable upon movement to open and close the contacts; and
 - (c.) a damper operable to dampen the movement of the shaft, the damper comprising:
 - a housing having a wall with an opening and defining an interior chamber into which the shaft extends, the interior chamber being in communication with the opening;

16

a piston disposed in the interior chamber and secured to the shaft so as to be movable therewith, the piston having one or more first openings and one or more second openings, the one or more first openings being larger than the one or more second openings;

a blocking structure disposed in the interior chamber such that the piston is disposed between the opening and the blocking structure, the blocking structure having a body through which the shaft movably extends, the blocking structure being movable between being proximate and distal to the piston, wherein when the blocking structure is proximate to the piston, the blocking structure closes the one or more first openings, but not the one or more second openings, and wherein when the blocking structure is distal to the piston, the blocking structure does not close either the one or more first openings or the one or more second openings;

a spring biasing the blocking structure toward the piston; wherein during the movement of the shaft to close the contacts, the blocking structure is disposed proximate to the piston; and

wherein when the shaft moves to open the contacts, the blocking structure moves against the bias of the spring to be distal from the piston, thereby opening the one or more first openings.

2. The on-load tap changer of claim 1, wherein the blocking structure comprises a flange joined to the body, and wherein when the blocking structure is proximate to the piston, the flange closes the one or more first openings.

3. The on-load tap changer of claim 2, wherein the body is cylindrical and has an axial bore through which the shaft extends, and wherein the flange is annular.

4. The on-load tap changer of claim 3, wherein the spring is helical and has a first end portion disposed around the body of the blocking structure.

5. The on-load tap changer of claim 3, wherein the blocking structure is a first blocking structure and wherein the damper further comprises a second blocking structure having an annular flange joined to a cylindrical body through which the shaft extends;

wherein the spring has a second end portion disposed around the body of the second blocking structure; and wherein the spring is trapped between the flanges of the first and second blocking structures.

6. The on-load tap changer of claim 5, wherein the shaft is movable through the body of the second blocking structure.

7. The on-load tap changer of claim 3, wherein the interior chamber is cylindrical.

8. The on-load tap changer of claim 1, wherein the one or more first openings comprises a plurality of first openings.

9. The on-load tap changer of claim 8, wherein the one or more second openings comprises a plurality of second openings.

10. The on-load tap changer of claim 9, wherein each of the first openings is kidney-shaped.

11. The on-load tap changer of claim 9, wherein each of the second openings is circular.

12. The on-load tap changer of claim 9, wherein the second openings are disposed outward from the first openings.

13. The on-load tap changer of claim 1, wherein the shaft comprises multiple sections removably fastened together.

14. The on-load tap changer of claim 1, wherein the actuation assembly comprises:

- a rotatable cam;
- a shuttle having a cam follower engaged with the cam such that rotation of the cam moves the shuttle;

17

an impact mass connected to the shuttle by springs such that the impact mass tends to follow the shuttle when the shuttle moves;

a holding device operable to hold and then release the impact mass when the shuttle starts to move, the holding of the impact mass when the shuttle starts to move causing the springs to store forces, which are released when the impact mass is released; and

wherein during the movement of the impact mass, the impact mass contacts the shaft and moves the shaft to open or close the contacts.

15. The on-load tap changer of claim **14**, wherein the shuttle further comprises a pair of first mounts joined to opposing sides of a body, respectively, and a pair of second mounts joined to opposing sides of the body, respectively, each of the first mounts and the second mounts having a bore extending therethrough; and

wherein the actuation assembly further comprises a pair of spaced-apart mounting rails, one of the mounting rails extending through the bores of one of the first mounts and one of the second mounts, and the other one of the mounting rails extending through the bores of the other one of the first mounts and the other one of the second mounts.

16. The on-load tap changer of claim **15**, wherein the cam follower is mounted to the body of the shuttle.

18

17. The on-load tap changer of claim **15**, wherein the impact mass comprises a pair of blocks, each of which has opposing first and second surfaces and a bore extending there-through; and

wherein the mounting rails extend through the bores in the blocks, respectively.

18. The on-load tap changer of claim **17**, wherein the one or more springs comprises:

a pair of first springs disposed between the first surfaces of the blocks of the impact mass and the first mounts of the shuttle, respectively; and

a pair of second springs disposed between the second surfaces of the blocks of the impact mass and the second mounts of the shuttle, respectively.

19. The on-load tap changer of claim **14**, wherein the holding device comprises first and second pawls pivotally mounted between a pair of pawl rails, each of the first and second pawls comprising a catch end and a release end, and wherein each of the first and second pawls is pivotable between an engaged position, wherein the catch end engages the impact mass so as to prevent its movement, and a disengaged position, wherein the catch end does not engage the impact mass.

20. The on-load tap change of claim **14**, wherein the shuttle and the impact mass are disposed between the vacuum interrupter and the damper.

* * * * *